



# Improving Spectrum Efficiency with $\mu$ ACKs

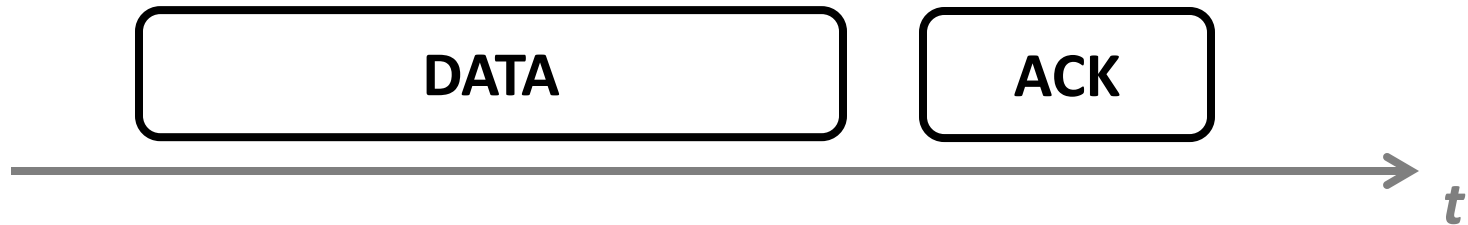
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Yongguang Zhang<sup>†</sup> and Qian Zhang<sup>#</sup>

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<sup>#</sup>HKUST

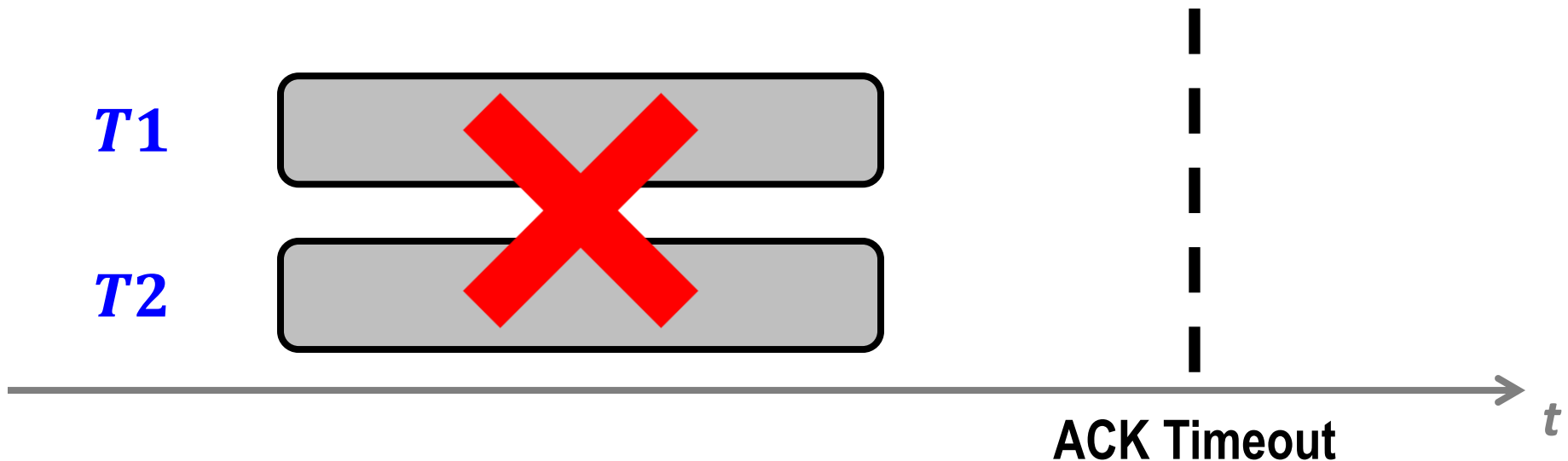
# Feedback in Wireless Networks



- Feedback is critical for network protocols
  - Confirm reception / detect loss (i.e. ACKs)
- Current network protocols are primarily based on frame level feedback

# Frame-level Feedback Considered Harmful in Wireless

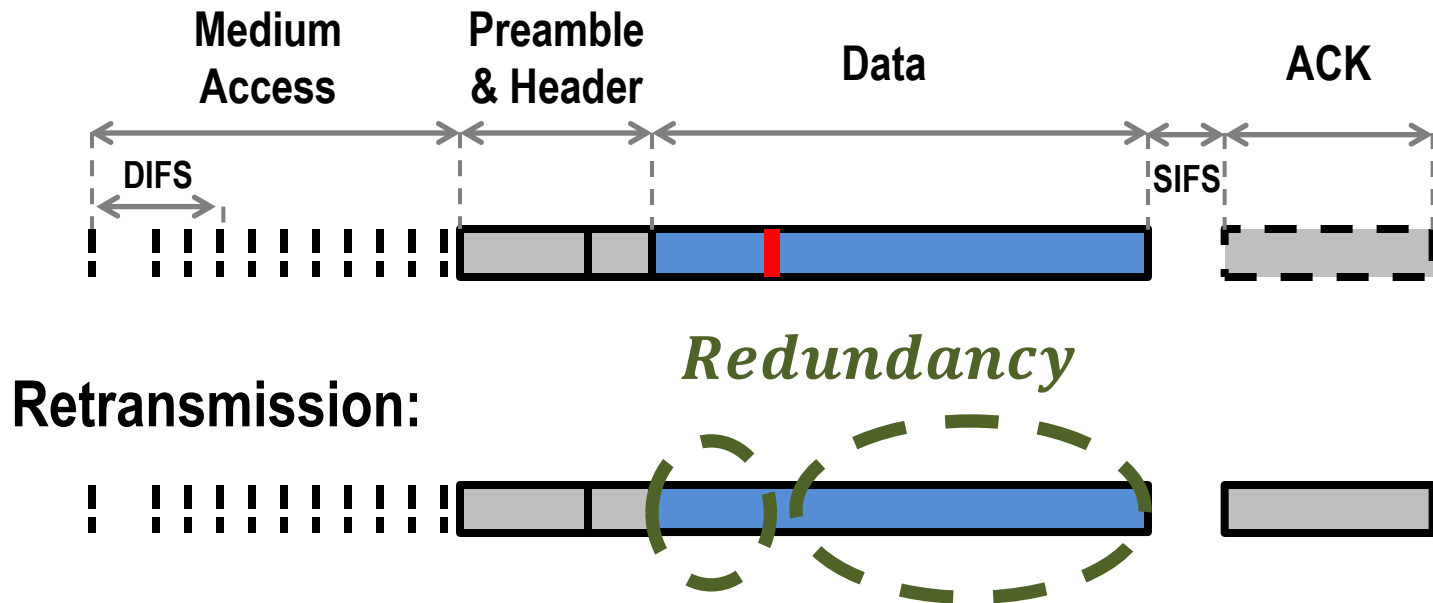
## Example 1: Collision detection based on ACK



- May be too late
  - Feedback received after all damage has been done

# Frame-level Feedback Considered Harmful in Wireless

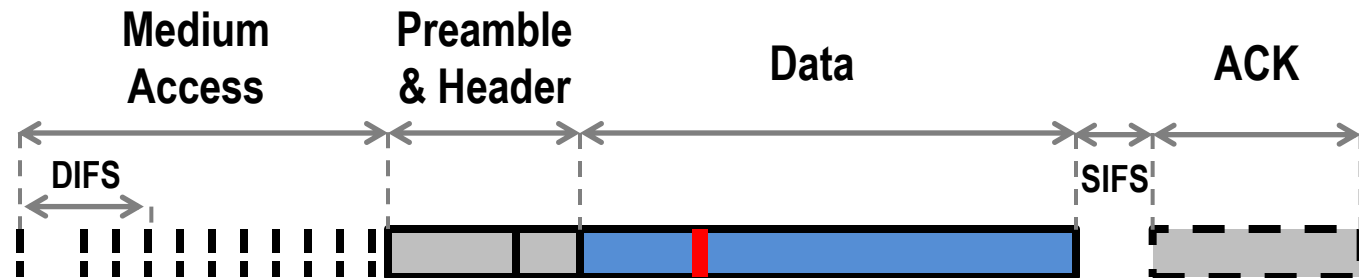
## Example 2: Frame retransmission is inefficient



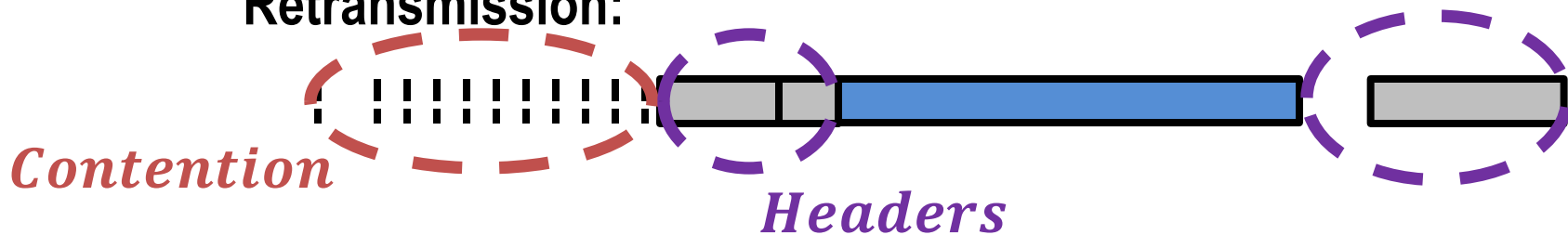
- May contain limited information

# Frame-level Feedback Considered Harmful in Wireless

## Example 2: Frame retransmission is inefficient



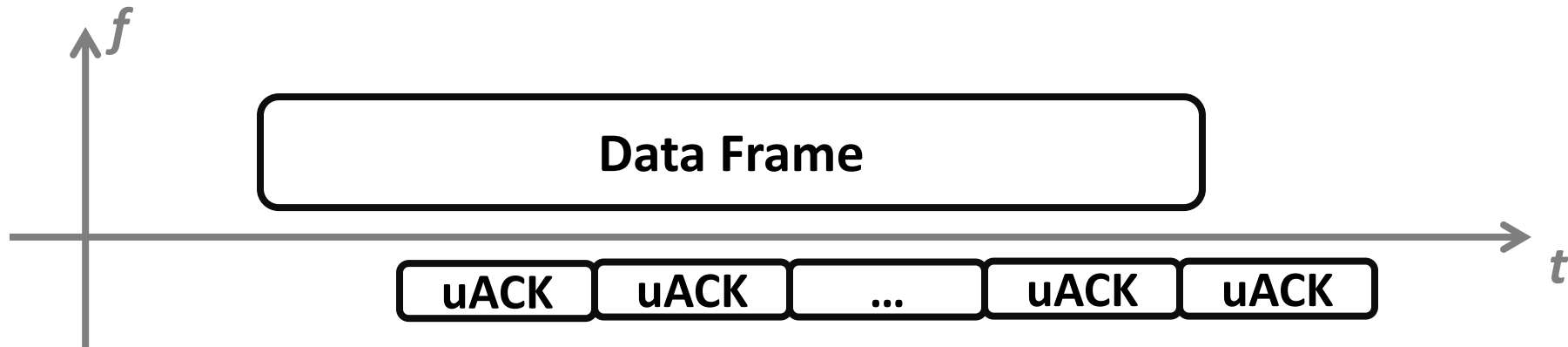
Retransmission:



- May contain limited information
- May be costly to re-establish transmission context

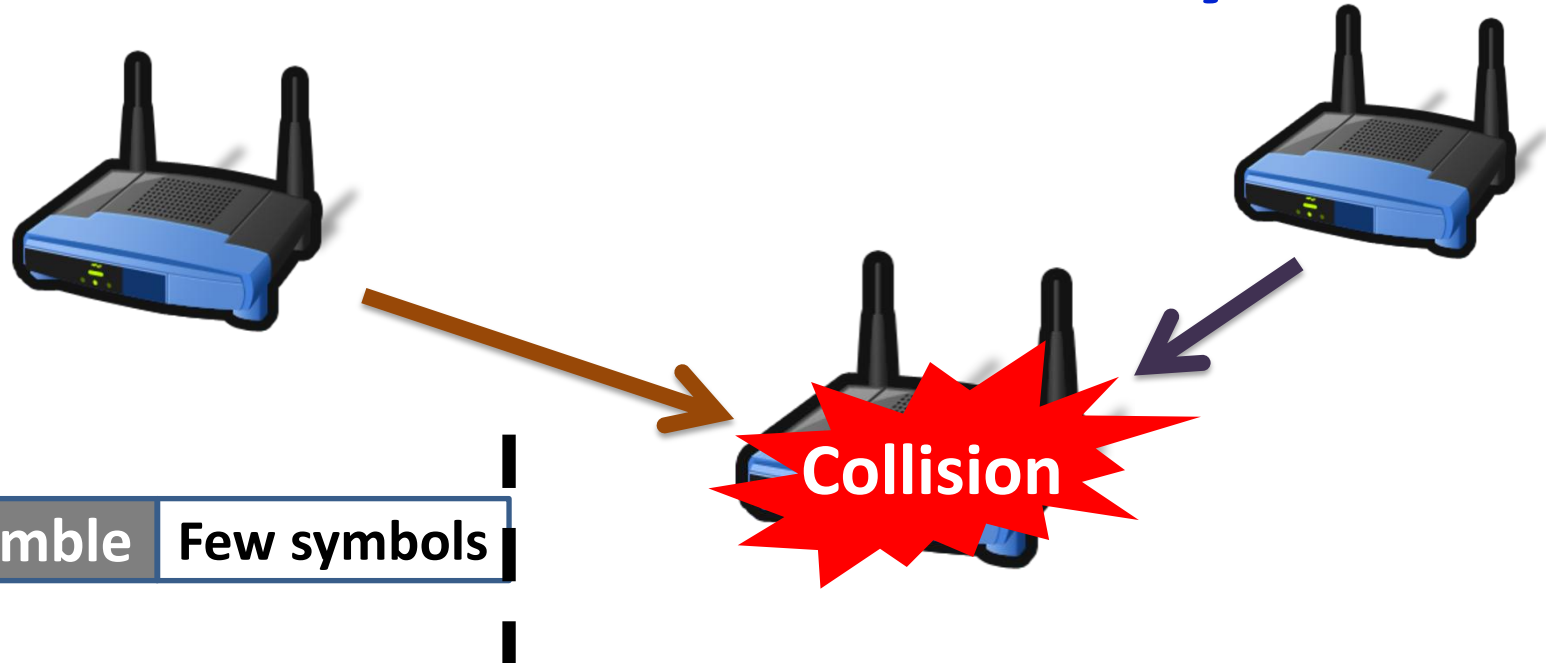
**We should do symbol level feedback**

# $\mu$ ACK Towards Symbol-level Feedback



- Two Tightly synchronized radio chains
  - Wide-band forward channel
  - Narrow-band feedback channel
- Tiny acknowledgement symbols

# $\mu$ ACK Application 1 – Collision Detection and Early Backoff

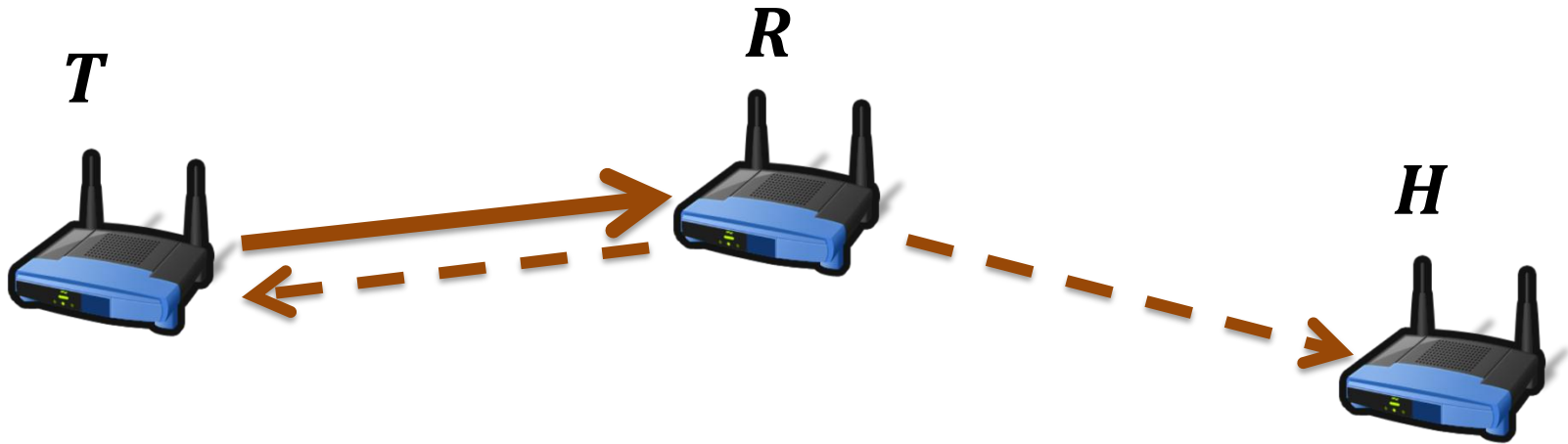


- Early collision detection by feedback timeout



# $\mu$ ACK Application 2 – Hidden & Exposed Terminal Mitigation

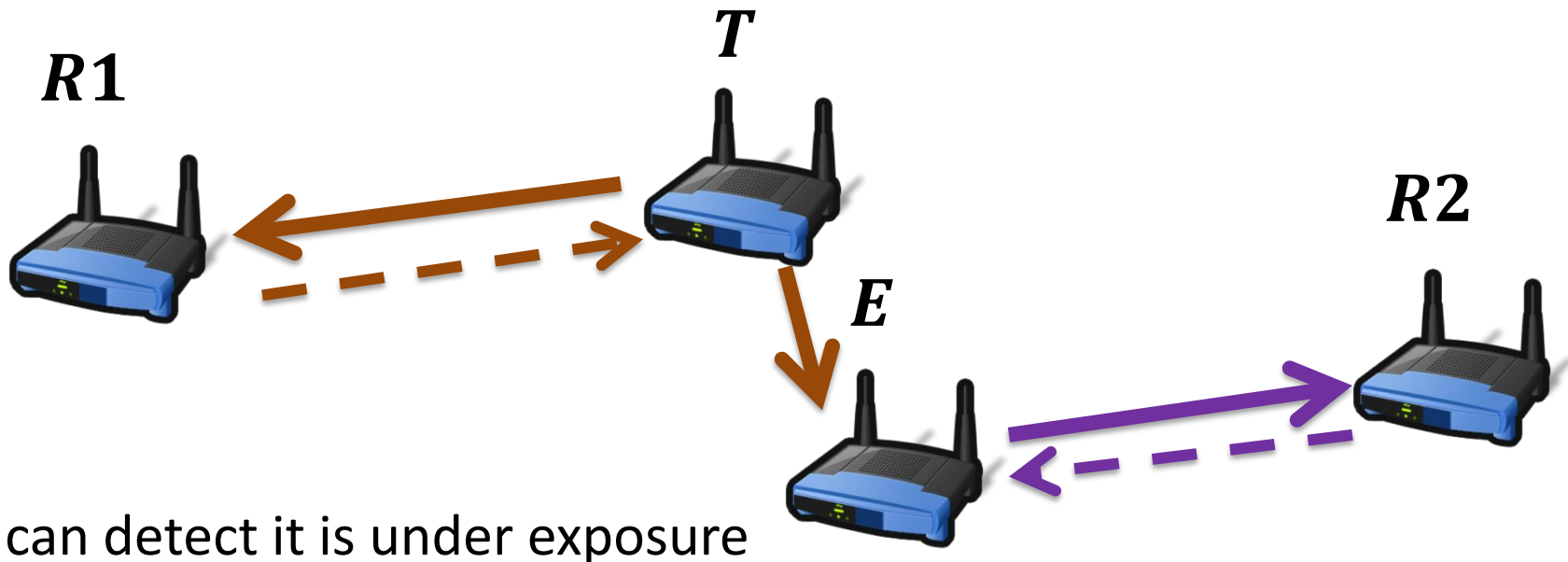
Hidden Terminal:



$\mu$ ACK from R prevents H from colliding

# $\mu$ ACK Application 2 – Hidden & Exposed Terminal Mitigation

Exposed Terminal:

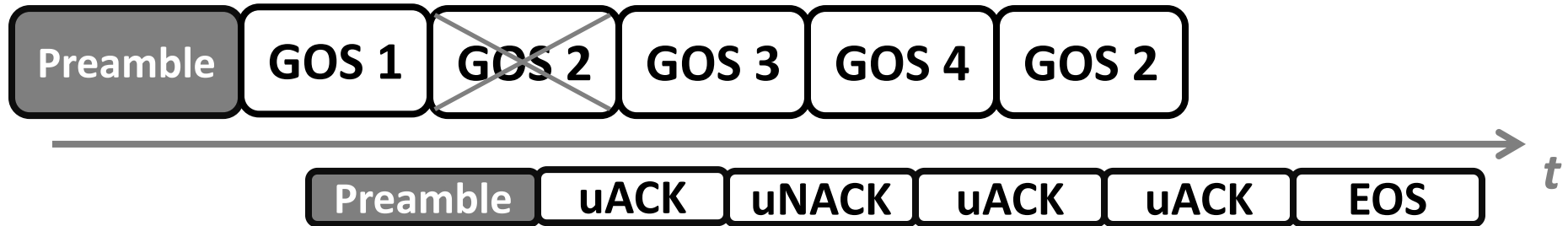


- $\mu$ ACK is an extended busy tone

# $\mu$ ACK Application 3 – In Frame Retransmission

GOS: group of symbols

EOS: end of stream



- Retransmission appends to original frame

# μACK Benefits Wireless in Various Ways

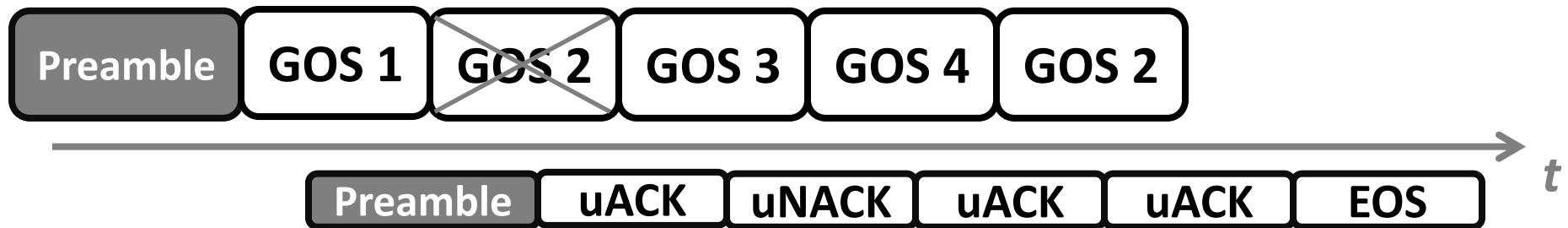
- Application 1:
  - Collision Detection and Early Backoff
- Application 2 (extended):
  - Hidden & Exposed Terminal Mitigation
- Application 3:
  - In-frame Retransmission

# μACK Benefits Wireless in Various Ways

- Application 1:
  - Collision Detection and Early Backoff
- Application 2 (extended):
  - Hidden & Exposed Terminal Mitigation
- Application 3:
  - In-frame Retransmission

# In-frame Retransmission Details

- Design questions
  - What is the symbol group size?
  - What is  $\mu ACK$  physical layer?
  - How to determines a group of symbol is correct?



**GOS: group of symbols**

**EOS: end of stream**

# Data Symbol Group Size

- Symbols in a group are fate-sharing
  - GOS length  $<$  coherent time of the channel
- Tradeoff between redundant bits and feedback channel requirement
  - Larger GOS  $\rightarrow$  more redundant bits, and less feedback bandwidth
- Design choice
  - $20\mu s$  GOS  $\rightarrow$  5 OFDM symbols
  - 1MHz feedback channel  $\sim$  5% for 20MHz data channel

# μACK PHY

- Simple spectrum spreading PHY
  - ❑ Feedback symbol time is  $20\mu s$  (the length of GOS)
  - ❑ Four bits per symbol (encode 3 states)
  - ❑ Channel width is 1MHz (50% guard band) → Bandwidth 500KHz → Chip rate is 500Kcps
  - ❑ Ten chips per symbol

Symbol name	Symbol binary ( $b_3b_2b_1b_0$ )	Chip values
ACK	1100	0111100010
NACK	1001	0011001101
EOS	0110	1100110110



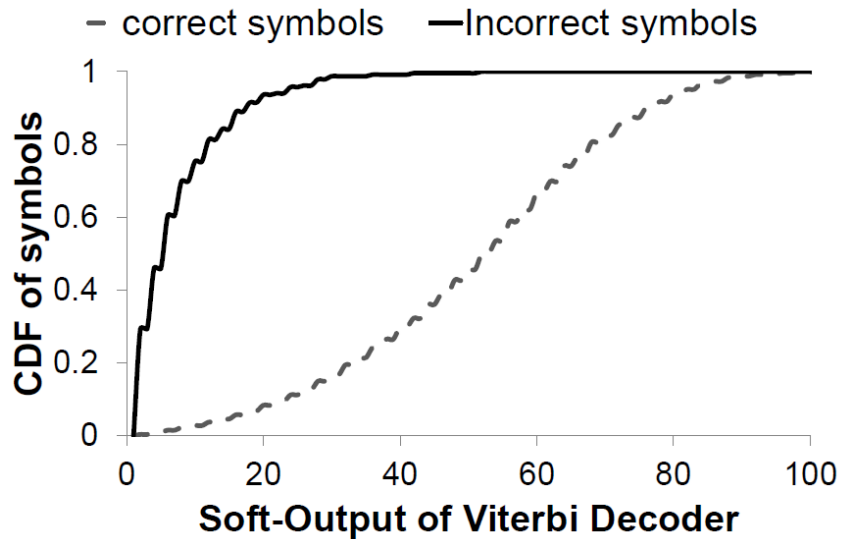
# Error Detection

- Two methods
  - Segment CRC (additional overhead)
  - PHY hints

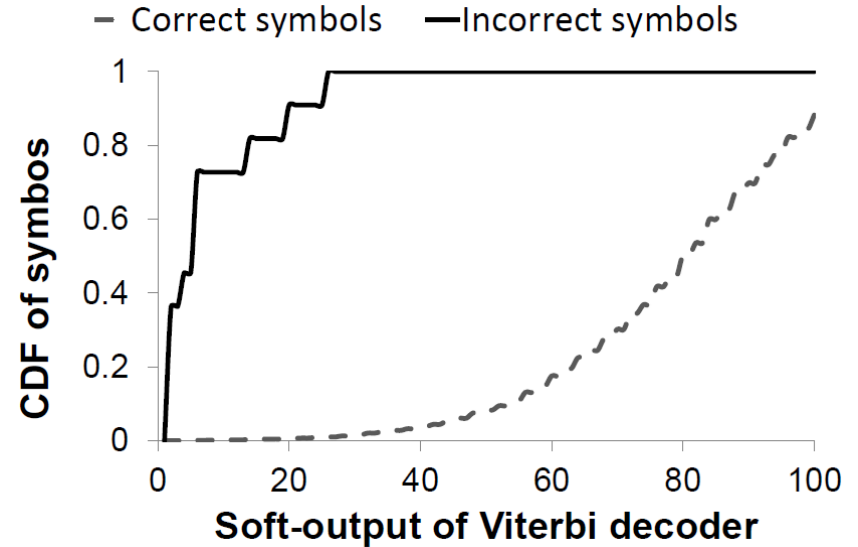
**We found PHY hints becomes less reliable in some cases ...**

# PHY hints become unreliable on marginal SNR

24Mbps, 10dB (marginal)

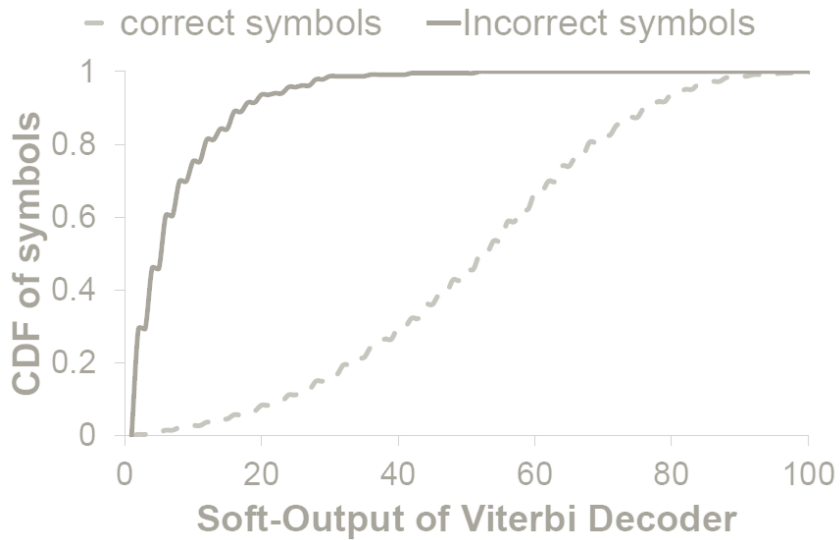


24Mbps, 12dB (higher)

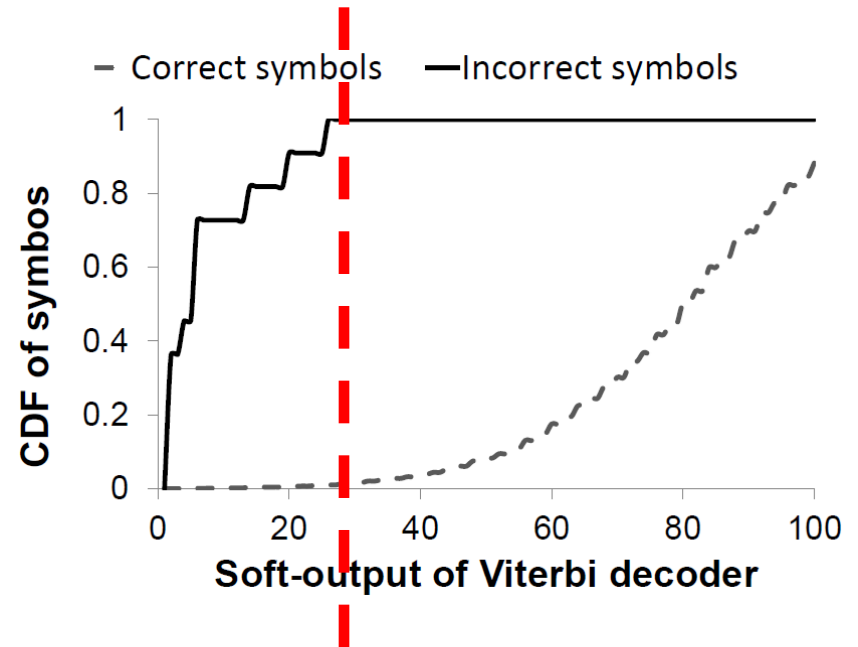


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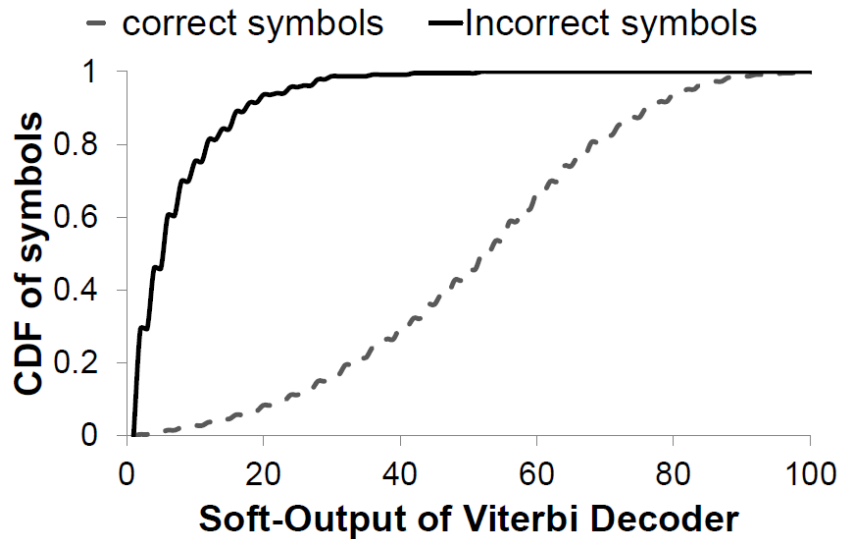


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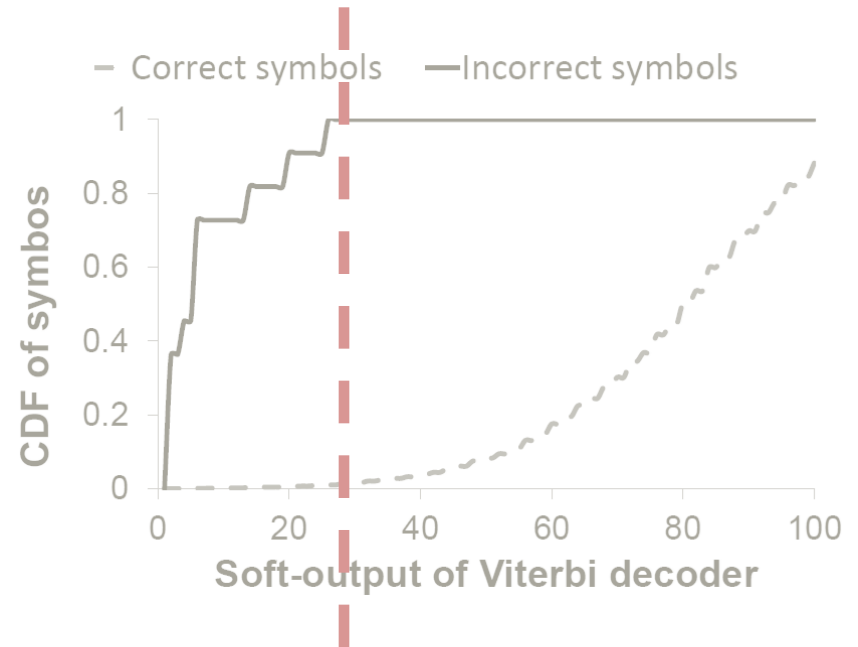


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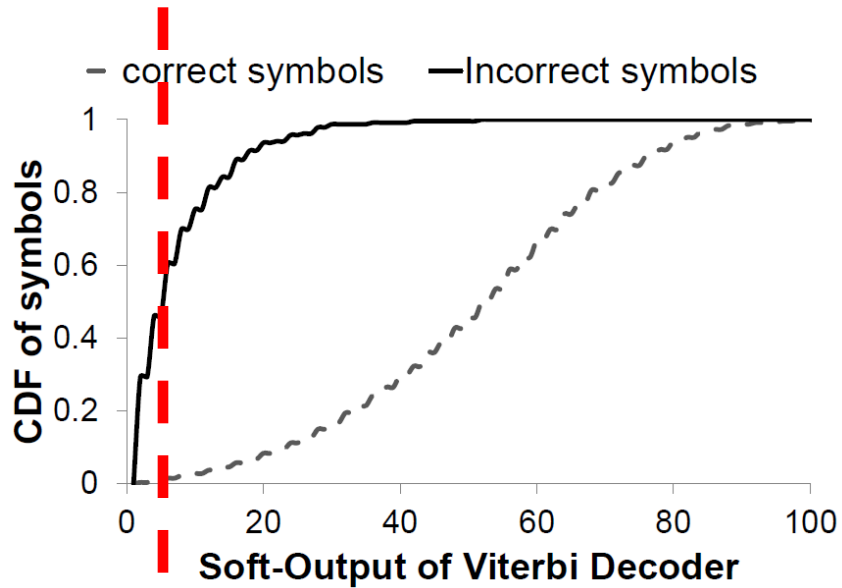


24Mbps, 12dB (higher)



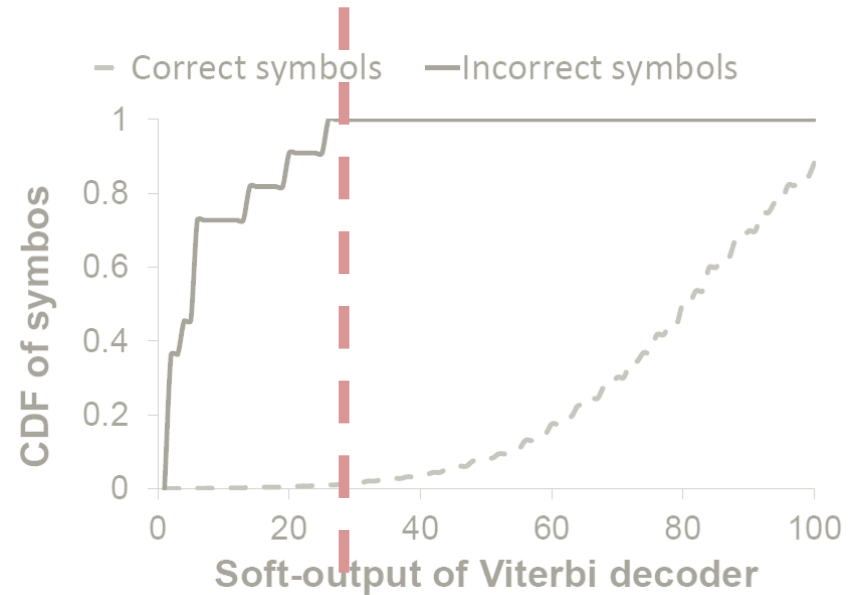
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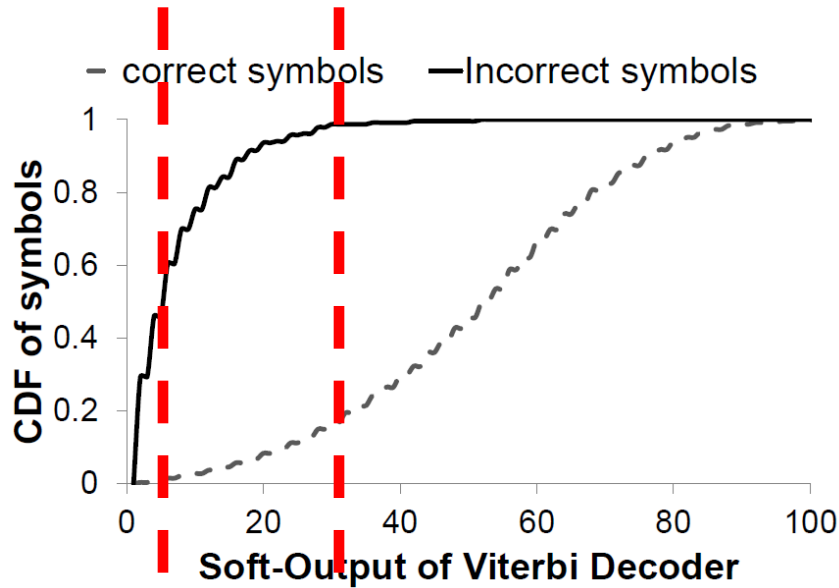
False  
negative

24Mbps, 12dB (higher)



# PHY hints become unreliable on marginal SNR

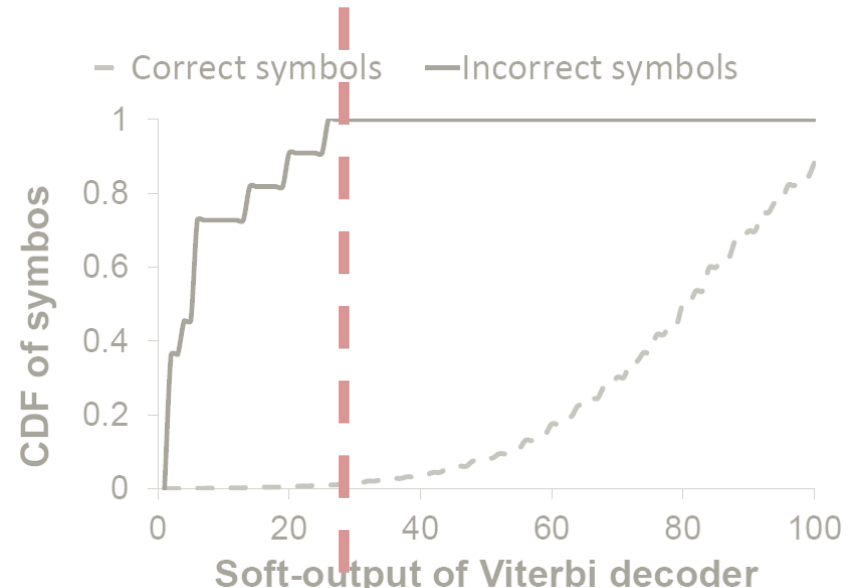
24Mbps, 10dB (marginal)



False  
negative

False  
positive

24Mbps, 12dB (higher)

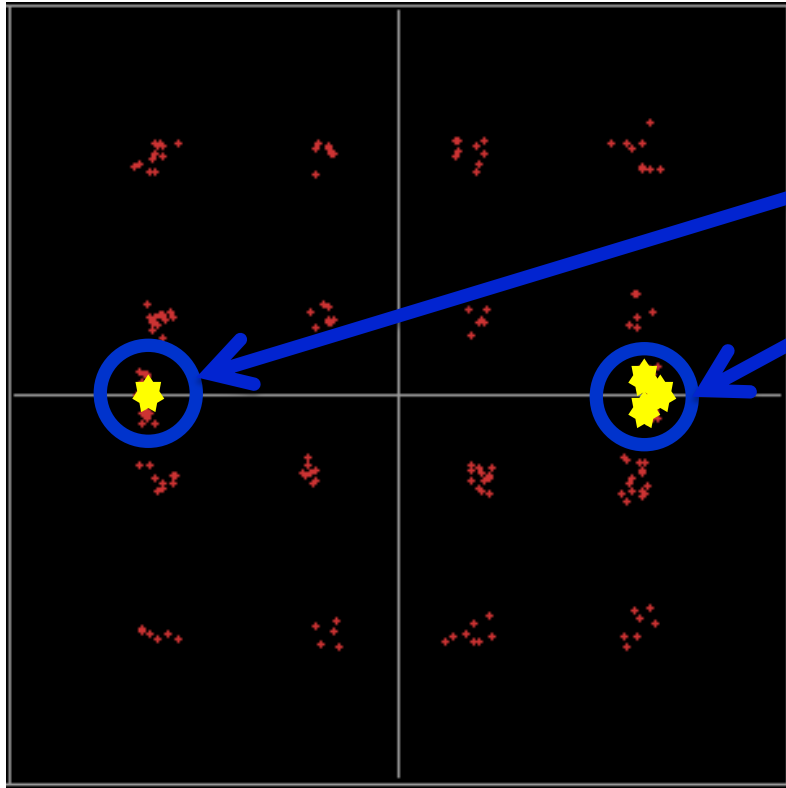


We explicitly embed CRC  
in each GOS

**Segment CRCs add additional overhead**

**Can we avoid the overhead?**

# Pilot Side-Channel



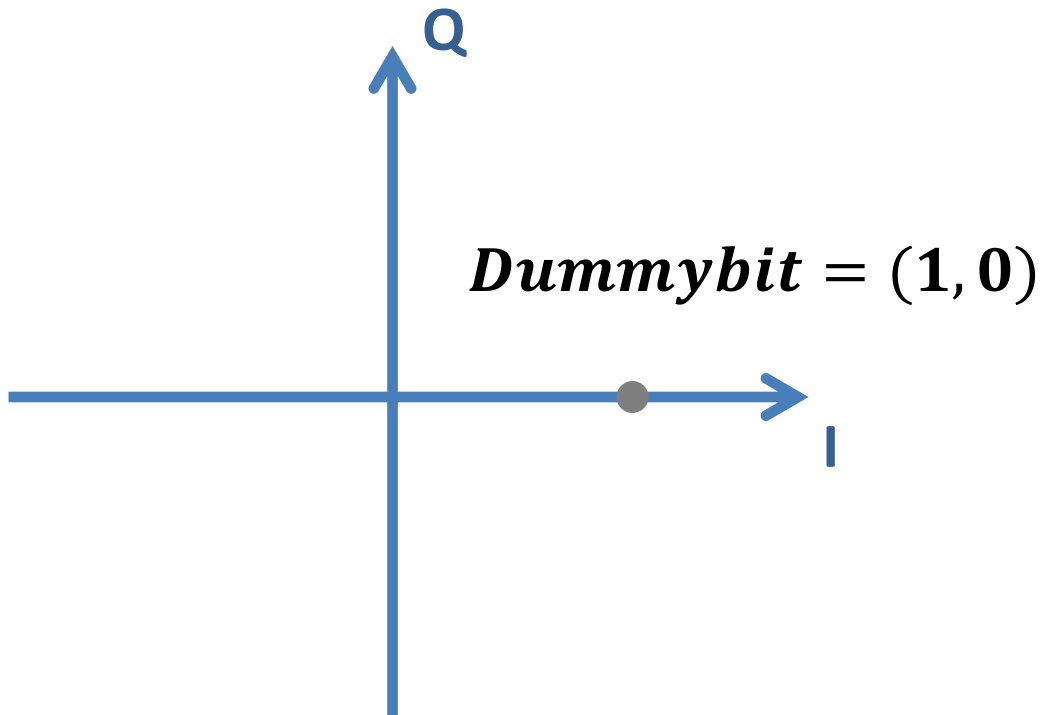
## Dummy-bit Pilots

- Encode information in the pilots
  - ❑ Embed 16 bits in a GOS
  - ❑ Hamming (16, 11) code
  - ❑ CRC-10



# Pilot Side-Channel

- How?
  - Differential BPSK  
(similar to 802.11b)

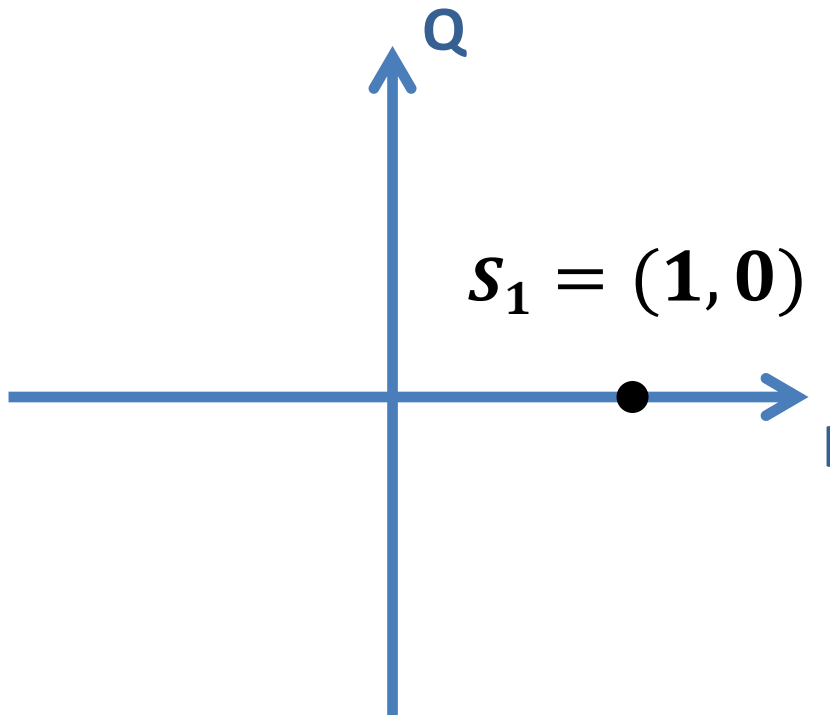


**Example:**

Symbol	Encoded	(I, Q)
$S_0$		(1, 0)

# Pilot Side-Channel

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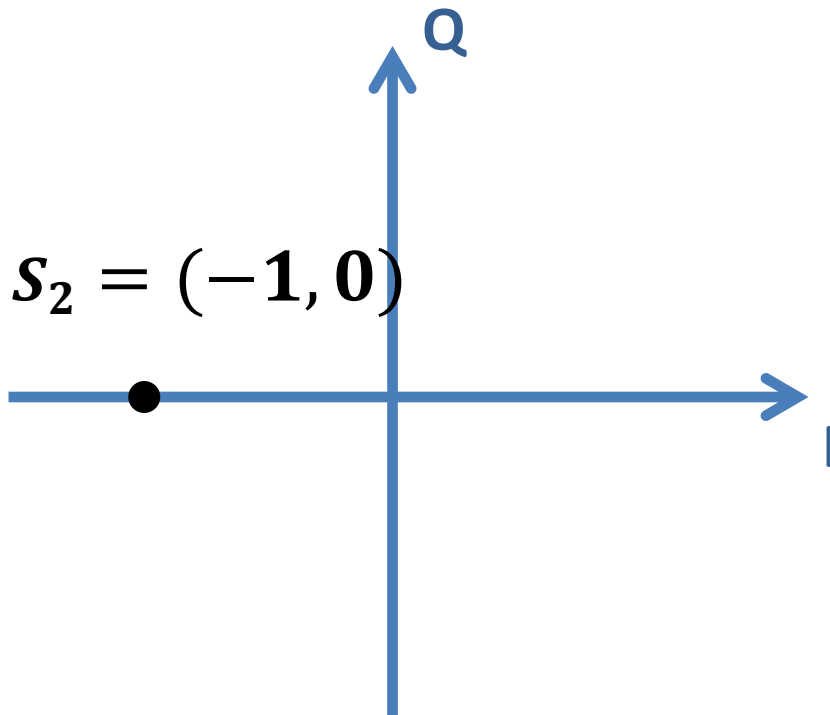


## Example:

Symbol	Encoded	(I, Q)
$s_0$		(1, 0)
$s_1$	0	(1, 0)

# Pilot Side-Channel

- How?
  - Differential BPSK  
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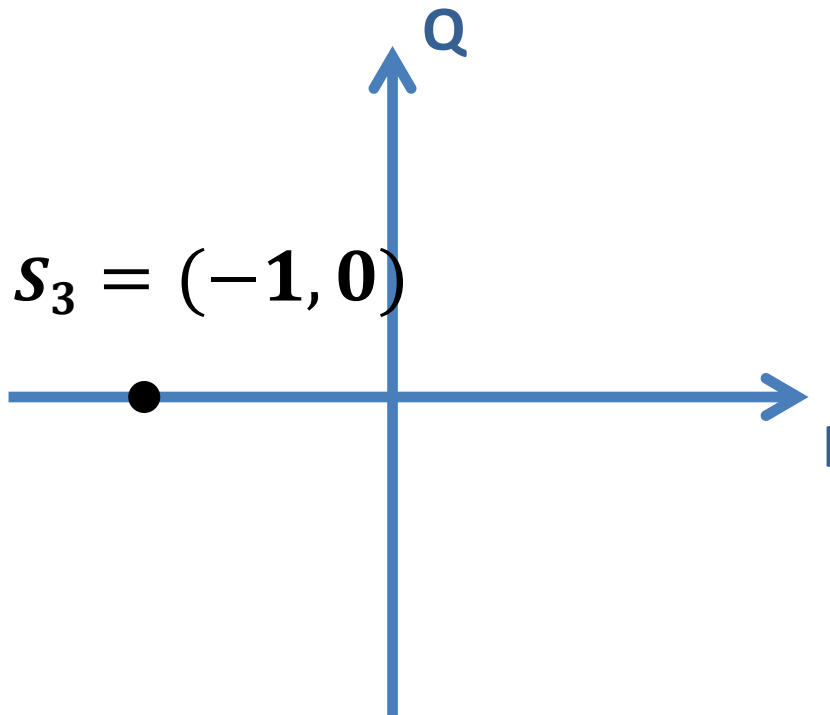


## Example:

Symbol	Encoded	(I, Q)
$S_0$		(1, 0)
$S_1$	0	(1, 0)
$S_2$	1	(-1, 0)

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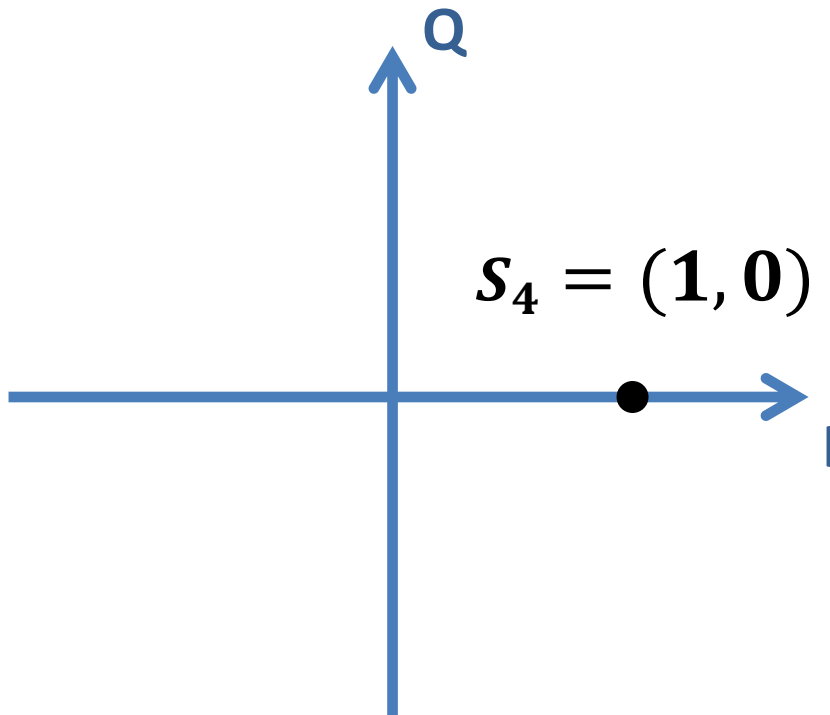


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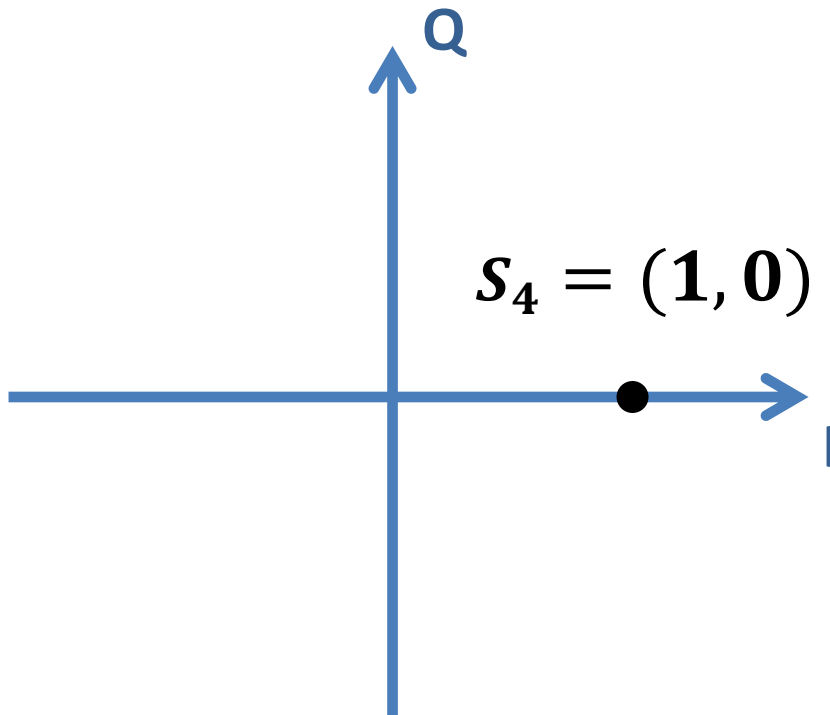


## Example:

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$S_0$		(1, 0)
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$S_3$	0	(-1, 0)
$S_4$	1	(1, 0)

# Pilot Side-Channel

- How?
  - Differential BPSK  
(similar to 802.11b)



## Example:

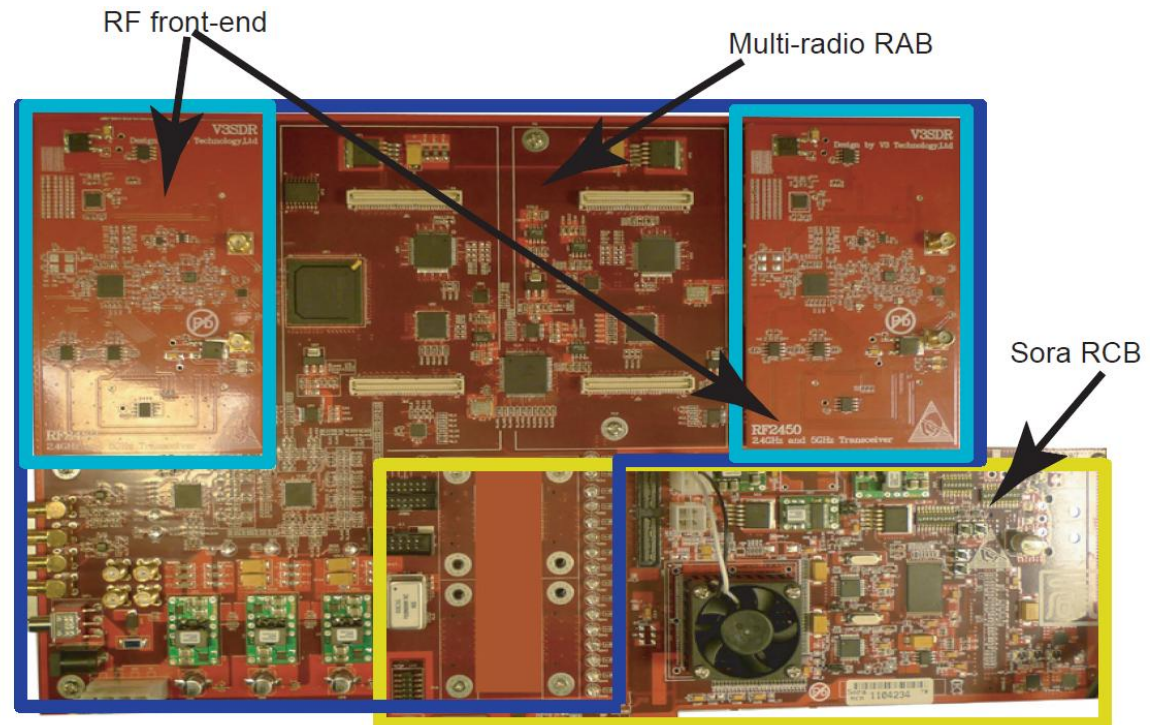
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$S_3$	0	(-1, 0)
$S_4$	1	(1, 0)
...	...	...

# Decision Directed Pilot Tracking

- Pilots should be decoded first before used for channel tracking
  - No performance loss if pilots are correctly decoded
  - No performance loss even if pilots are not correctly decoded
- Normal pilots are inserted at beginning of an GOS
  - Pilot decision error will not propagate to next GOS

# Sora Based Implementation

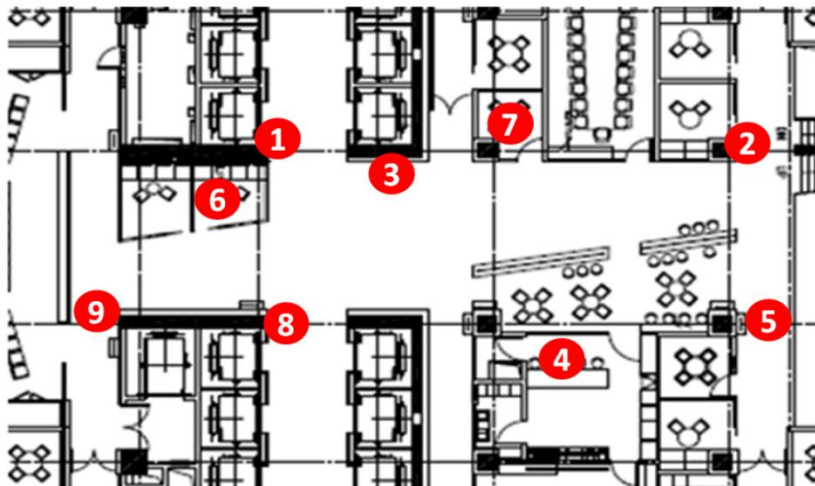
- Extend Sora
  - Multi-radio board
  - Direct symbol transmission to radio



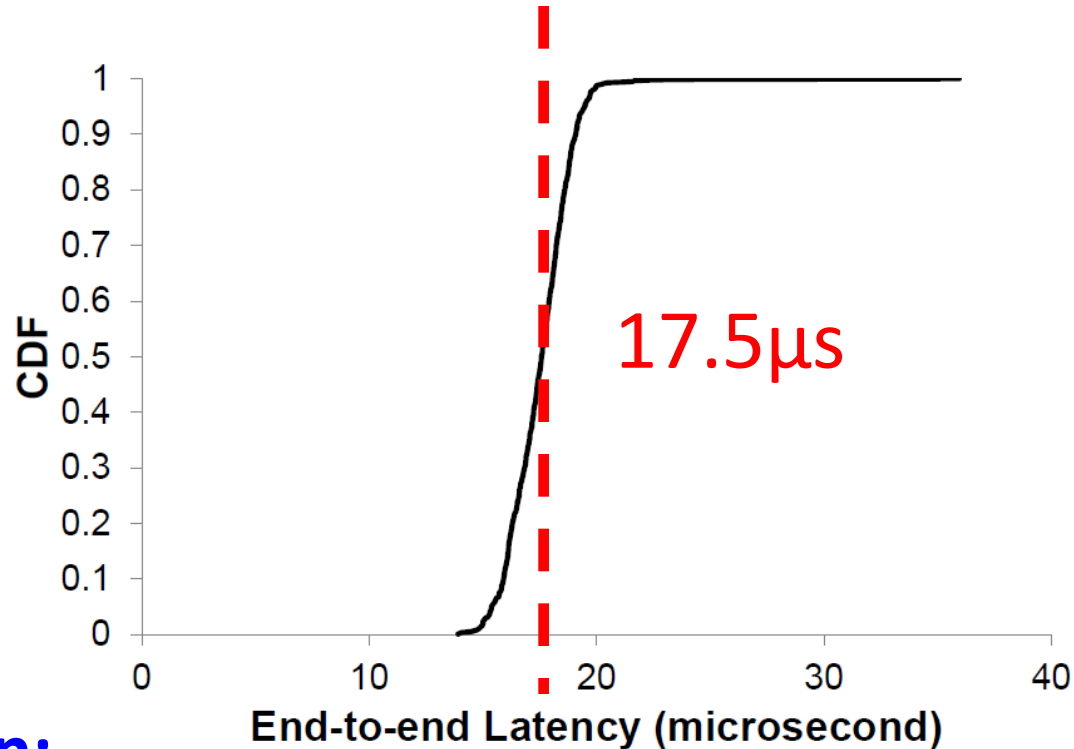


# Performance Evaluation

- Is  $\mu$ ACK feasible?
  - Micro-benchmarks
- What is the benefit of  $\mu$ ACK?
  - Wired single link
  - 9 node real network



# End-to-end Latency of $\mu$ ACK

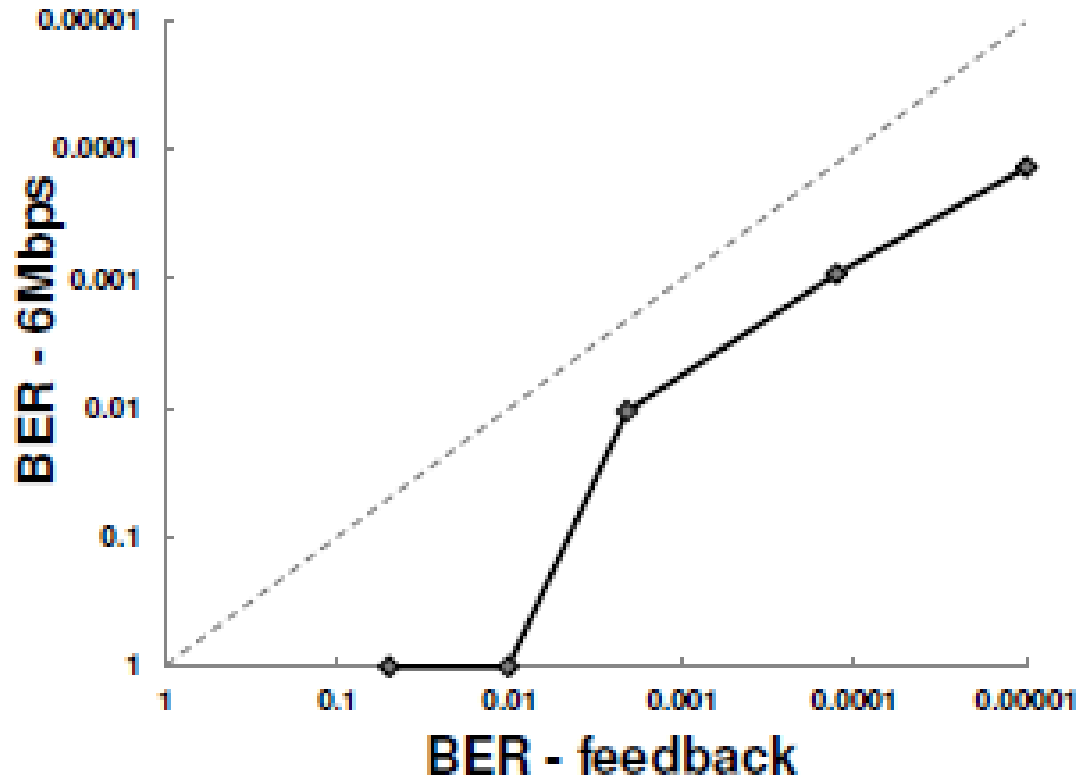


## Breakdown:

Viterbi Decoding	$\mu$ ACK modulation	Hardware
7.5 $\mu$ s	1.96 $\mu$ s	9.103 $\mu$ s

# $\mu$ ACK PHY Performance

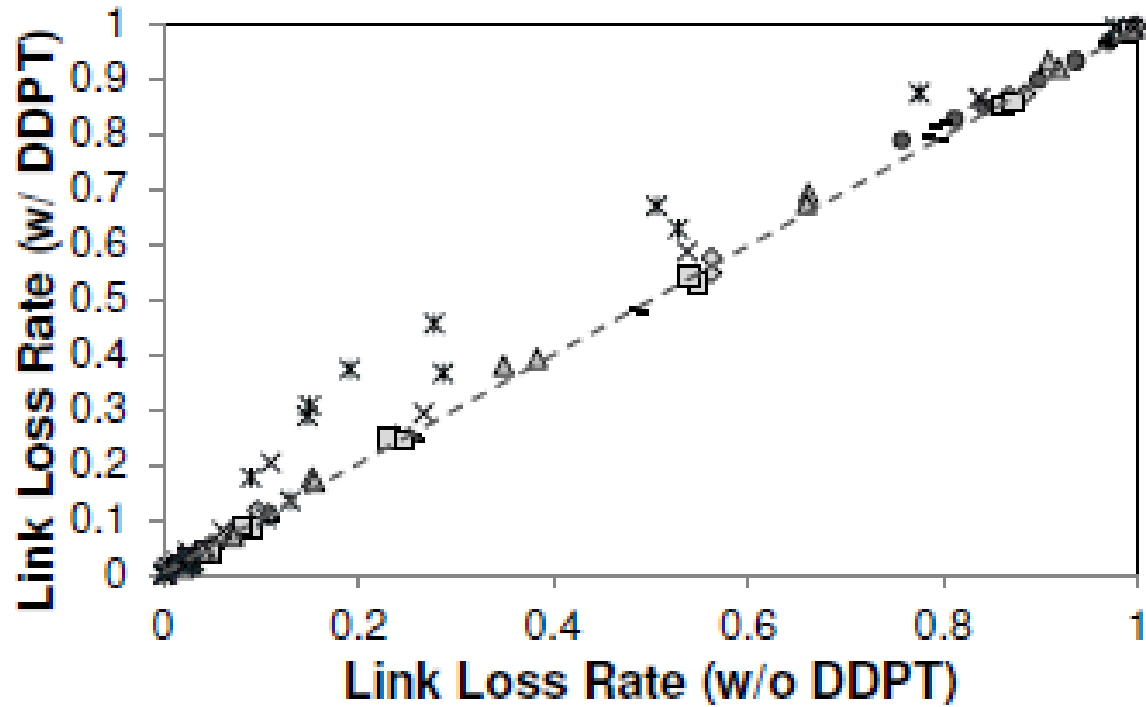
- $\mu$ ACK vs. 802.11 6Mbps



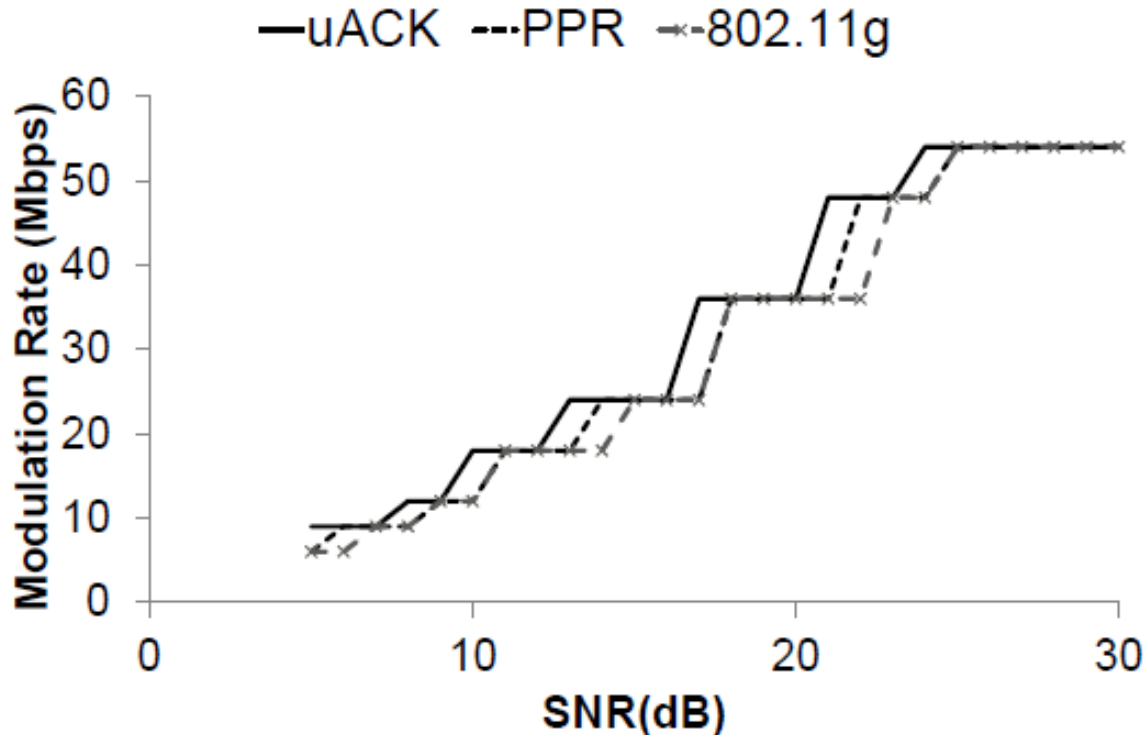
# DDPT Performance

## ■ DDPT vs. Normal

● 54Mbps - 36Mbps ◇ 24Mbps □ 18Mbps  
△ 12Mbps × 9Mbps × 6Mbps



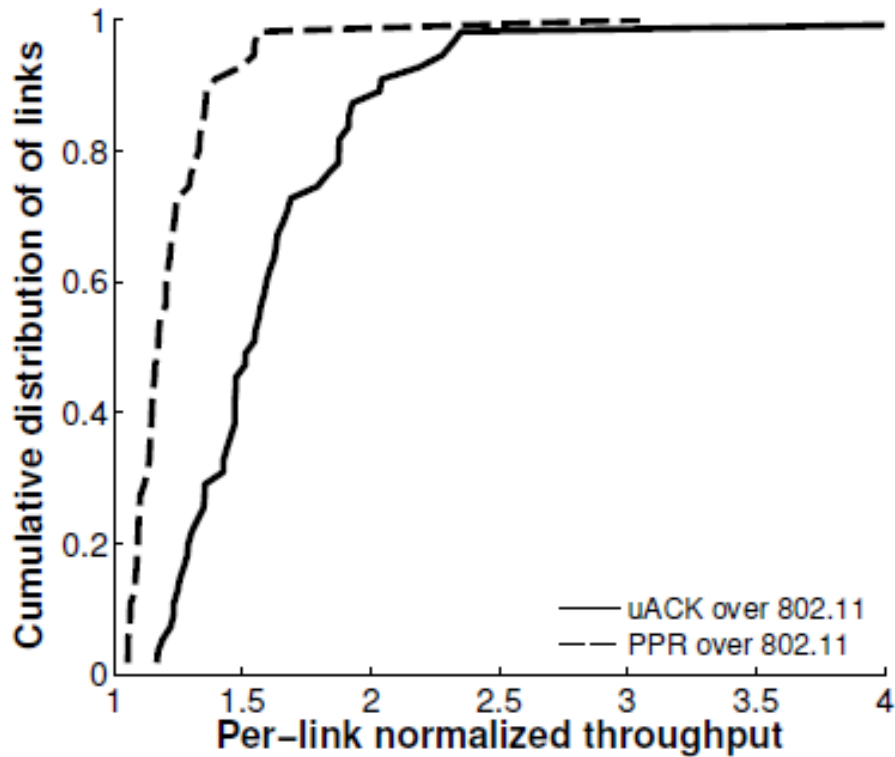
# $\mu$ ACK on Wired Single Link



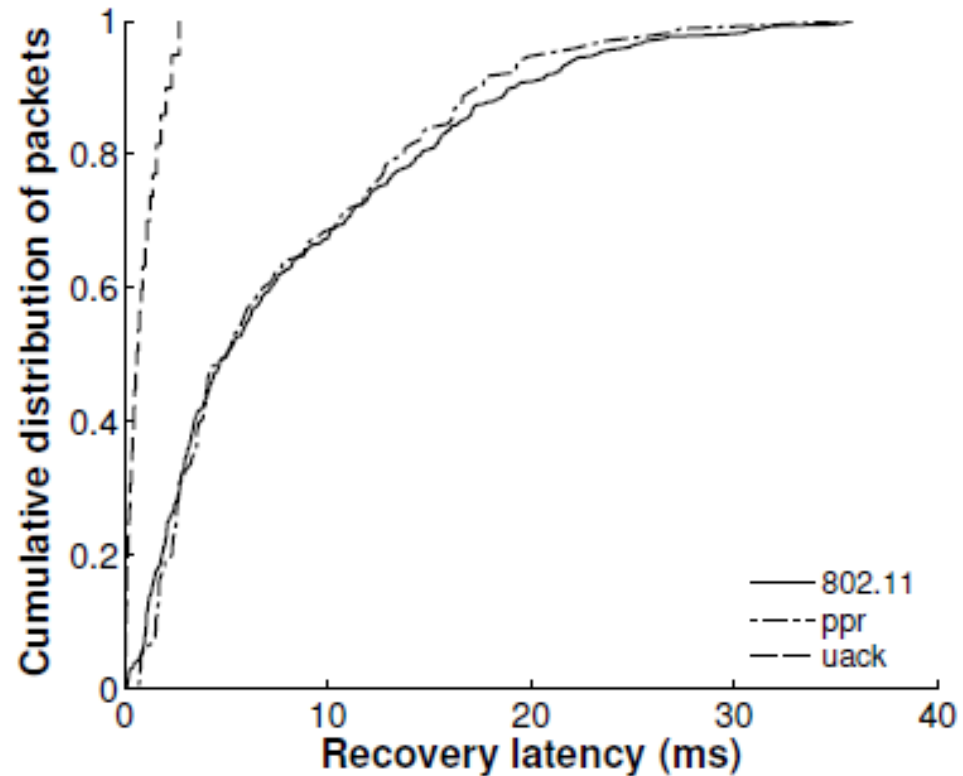
- $\mu$ ACK sender aggressively use higher data rates.
- Up to 220% over 802.11a, up to 30% over PPR

# Trace-based Emulation

## Throughput



## Latency



# Related Work

- Hybrid ARQs
  - Complementary to  $\mu ACK$
- Partial Packet Recovery
- CSMA/CN
- Rate adaptation
  - $\mu ACK$  shows by reducing loss recovery overhead, one can use more aggressive rates
  - $\mu ACK$  also enables in-frame rate adaptation
- Busy-tone schemes (DBTMA)
  - $\mu ACK$  can serve as an extended busy tone

# Conclusion

- $\mu ACK$  enables sending fine-grained feedback
  - Collision detection
  - Mitigation of hidden & exposed terminal problem
  - In-frame loss recovery
- $\mu ACK$  is feasible & significantly improves spectrum efficiency
  - Reduces retransmission overhead
  - Increases transmission rate
  - Improves collision management