

# Learning from the Wisdom of Crowds by Minimax Entropy

Denny Zhou, John Platt, Sumit Basu and Yi Mao  
Microsoft Research, Redmond, WA

# Outline

1. Introduction
2. Minimax entropy principle
3. Future work and conclusion

# 1. Introduction

# Machine Learning Meets Crowdsourcing

- To Improve a machine learning model:
  - Add more training examples
  - Create more meaningful features
  - Invent more powerful learning algorithms

More and more efforts, less and less gain

# Machine Learning Meets Crowdsourcing

- To Improve a machine learning model:
  - Adding more training examples
  - Creating more meaningful features
  - Inventing more powerful learning algorithms

More and more efforts, less and less gain

# Crowdsourcing for Labeling



# Low Cost, but also Low Quality



**Norfolk Terrier**

**Norwich Terrier**

**Image Labeling**  
Average worker accuracy: 68%



**Irish Wolfhound**

**Scottish Deerhound**

**(Stanford dogs dataset)**

# Problem Setting and Notations

Workers:  $i = 1, 2, \dots, m$

Items:  $j = 1, 2, \dots, n$

Categories:  $k = 1, 2, \dots, c$

Response matrix  $Z_{m \times n \times c}$

- $z_{ijk} = 1$ , if worker  $i$  labels item  $j$  as category  $k$
- $z_{ijk} = 0$ , if worker  $i$  labels item  $j$  as other (not  $k$ )
- $z_{ijk} = \text{unknown}$ , if worker  $i$  does not label item  $j$

**Goal: Estimate the ground truth  $\{y_{jk}\}$**



# Toy Example: Binary Labeling

	Item 1	Item 2	Item 3	Item 4	Item 5	Item 6
Worker 1	1	2	1	1	1	2
Worker 2	2	2	1	2	1	1
Worker 3	1	1	2	1	1	2
Worker 4	1	1	1	1	1	2
Worker 5	1	1	1	2	2	2

**Problem: What are the true labels of the items?**

# A Simple Method: Majority Voting

	Item 1	Item 2	Item 3	Item 4	Item 5	Item 6
Worker 1	1	2	1	1	1	2
Worker 2	2	2	1	2	1	1
Worker 3	1	1	2	1	1	2
Worker 4	1	1	1	1	1	2
Worker 5	1	1	1	2	2	2

**By majority voting, the true label of item 4 should be class 1:**

# {workers labeling it as class 1} = 3

# {workers labeling it as class 2} = 2

Improve: More skillful workers should have more weight

# Dawid & Skene's Method

- Assume that each worker is associated with a  $c \times c$  confusion matrix

$$\{p_{kl}^{(i)} = \text{Prob}[z_{ij} = l | y_j = k, i]\}$$

- For any labeling task, the label by a worker is generated according to her confusion matrix

- Maximum Likelihood Estimation (MLE): jointly estimate confusion matrices and ground truth
- Implementation: EM algorithm

# Probabilistic Confusion Matrices

	Item 1	Item 2	Item 3	Item 4	Item 5	Item 6
Worker 1	1	2	1	1	1	2
Worker 2	2	2	1	2	1	1
Worker 3	1	1	2	1	1	2
Worker 4	1	1	1	1	1	2
Worker 5	1	1	1	2	2	2

**Assume that the true labels are:**

Class 1 = {item 1, item 2, item 3}

Class 2 = {item 4, item 5, item 6}

	Class 1	Class 2
Class 1	1	0
Class 2	2/3	1/3

# EM in Dawid & Skene's Method

- Initialize the ground truth by majority vote
- Iterate the following procedure till converge:
  - Estimate the worker confusion by using the estimated ground truth
  - Estimate the ground truth by using the estimated worker confusion

# Simplified Dawid & Skene's Method

Each worker  $i$  is associated with a single number  $p_i \in [0,1]$  such that

$$\text{Prob}[z_{ij} = y_j | i] = p_i$$

$$\text{Prob}[z_{ij} \neq y_j | i] = 1 - p_i$$

# Simplified Dawid & Skene's Method

Each worker  $i$  is associated with a single number  $p_i \in [0,1]$  such that

$$\text{Prob}[z_{ij} = y_j | i] = p_i$$

$$\text{Prob}[z_{ij} \neq y_j | i] = 1 - p_i$$



worker



coin

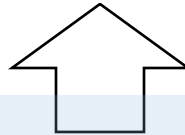
## 2. Minimax Entropy Principle



# Our Basic Assumption

	item 1	item 2	...	item $n$
worker 1	$z_{11}$	$z_{12}$	...	$z_{1n}$
worker 2	$z_{21}$	$z_{22}$	...	$z_{2n}$
...	...	...	...	...
worker $m$	$z_{m1}$	$z_{m2}$	...	$z_{mn}$

Observed labels

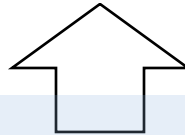


	item 1	item 2	...	item $n$
worker 1	$\pi_{11}$	$\pi_{12}$	...	$\pi_{1n}$
worker 2	$\pi_{21}$	$\pi_{22}$	...	$\pi_{2n}$
...	...	...	...	...
worker $m$	$\pi_{m1}$	$\pi_{m2}$	...	$\pi_{mn}$

unobserved distributions

# Our Basic Assumption

	item 1	item 2	...	item $n$
worker 1	$z_{11}$	$z_{12}$	...	$z_{1n}$
worker 2	$z_{21}$	$z_{22}$	...	$z_{2n}$
...	...	...	...	...
worker $m$	$z_{m1}$	$z_{m2}$	...	$z_{mn}$



	item 1	item 2	...	item $n$
worker 1	$\pi_{11}$	$\pi_{12}$	...	$\pi_{1n}$
worker 2	$\pi_{21}$	$\pi_{22}$	...	$\pi_{2n}$
...	...	...	...	...
worker $m$	$\pi_{m1}$	$\pi_{m2}$	...	$\pi_{mn}$

Separated distribution per work-item!

# Our Basic Assumption



	item 1	item 2	...	item $n$
worker 1	$z_{11}$	$z_{12}$	...	$z_{1n}$
worker 2	$z_{21}$	$z_{22}$	...	$z_{2n}$
...	...	...	...	...
worker $m$	$z_{m1}$	$z_{m2}$	...	$z_{mn}$



	item 1	item 2	...	item $n$
worker 1	$\pi_{11}$	$\pi_{12}$	...	$\pi_{1n}$
worker 2	$\pi_{21}$	$\pi_{22}$	...	$\pi_{2n}$
...	...	...	...	...
worker $m$	$\pi_{m1}$	$\pi_{m2}$	...	$\pi_{mn}$

Separated distribution per work-item!

# Maximum Entropy

- To estimate a distribution, it is typical to use the maximum entropy principle

$$\max_{\pi} - \sum_{i=1}^m \sum_{j=1}^n \sum_{k=1}^c \pi_{ijk} \ln \pi_{ijk}$$



E. T. Jaynes

# Column and Row Matching Constraints

	item 1	item 2	...	item $n$
worker 1	$z_{11}$	$z_{12}$	...	$z_{1n}$
worker 2	$z_{21}$	$z_{22}$	...	$z_{2n}$
...	...	...	...	...
worker $m$	$z_{m1}$	$z_{m2}$	...	$z_{mn}$

	item 1	item 2	...	item $n$
worker 1	$\pi_{11}$	$\pi_{12}$	...	$\pi_{1n}$
worker 2	$\pi_{21}$	$\pi_{22}$	...	$\pi_{2n}$
...	...	...	...	...
worker $m$	$\pi_{m1}$	$\pi_{m2}$	...	$\pi_{mn}$

# Column Constraints

$$\sum_{i=1}^m \pi_{ijk} = \sum_{i=1}^m z_{ijk}$$

**For each item:**

Count # workers labeling it as class 1

Count # workers labeling it as class 2

column matching

	Item 1	Item 2	Item 3	Item 4	Item 5	Item 6
Worker 1	1	2	1	1	1	2
Worker 2	2	2	1	2	1	1
Worker 3	1	1	2	1	1	2
Worker 4	1	1	1	1	1	2
Worker 5	1	1	1	2	2	2

# Row Constraints

$$\sum_{j=1}^n y_{jl} \pi_{ijk} = \sum_{j=1}^n y_{jl} z_{ijk}$$

row matching

**For each worker:**

Count # misclassifications from class 1 to 2

Count # misclassifications from class 2 to 1

	Item 1	Item 2	Item 3	Item 4	Item 5	Item 6
Worker 1	1	2	1	1	1	2
Worker 1	2	2	1	2	1	1
Worker 3	1	1	2	1	1	2
Worker 4	1	1	1	1	1	2
Worker 5	1	1	1	2	2	2

# Maximum Entropy

$$\max_{\pi} \quad - \sum_{i=1}^m \sum_{j=1}^n \sum_{k=1}^c \pi_{ijk} \ln \pi_{ijk}$$

Subject to

$$\sum_{i=1}^m \pi_{ijk} = \sum_{i=1}^m z_{ijk} \quad (\text{column constraint})$$

$$\sum_{j=1}^n y_{jl} \pi_{ijk} = \sum_{j=1}^n y_{jl} z_{ijk} \quad (\text{row constraint})$$



# To Estimate True Labels, Can We ...

$$\boxed{\max_y} \max_{\pi} - \sum_{i=1}^m \sum_{j=1}^n \sum_{k=1}^c \pi_{ijk} \ln \pi_{ijk}$$

Subject to

$$\sum_{i=1}^m \pi_{ijk} = \sum_{i=1}^m z_{ijk} \quad (\text{column constraint})$$

$$\sum_{j=1}^n y_{jl} \pi_{ijk} = \sum_{j=1}^n y_{jl} z_{ijk} \quad (\text{row constraint})$$

# To Estimate True Labels, Can We ...

$$\boxed{\max_y} \max_{\pi} - \sum_{i=1}^m \sum_{j=1}^n \sum_{k=1}^c \pi_{ijk} \ln \pi_{ijk}$$

Subject to

$$\sum_{i=1}^m \pi_{ijk} = \sum_{i=1}^m z_{ijk} \quad (\text{column constraint})$$

$$\sum_{j=1}^n y_{jl} \pi_{ijk} = \sum_{j=1}^n y_{jl} z_{ijk} \quad (\text{row constraint})$$

Leading to a uniform distribution for  $\{y_{jl}\}$

# To Estimate True Labels, Can We ...

$$\max_y \max_{\pi} - \sum_{i=1}^m \sum_{j=1}^n \sum_{k=1}^c \pi_{ijk} \ln \pi_{ijk}$$

Subject to

$$\sum_{i=1}^m \pi_{ijk} = \sum_{i=1}^m z_{ijk} \quad (\text{column constraint})$$

$$\sum_{j=1}^n y_{jl} \pi_{ijk} = \sum_{j=1}^n y_{jl} z_{ijk} \quad (\text{row constraint})$$

Leading to a uniform distribution for  $\{y_{jl}\}$

# Minimax Entropy Principle

$$\min_y \max_{\pi} - \sum_{i=1}^m \sum_{j=1}^n \sum_{k=1}^c \pi_{ijk} \ln \pi_{ijk}$$

Subject to

$$\sum_{i=1}^m \pi_{ijk} = \sum_{i=1}^m z_{ijk} \quad (\text{column constraint})$$

$$\sum_{j=1}^n y_{jl} \pi_{ijk} = \sum_{j=1}^n y_{jl} z_{ijk} \quad (\text{row constraint})$$

making  $\pi_{ij}$  “peaky” means that  $z_{ij}$  is the least random given  $y_{jl}$ .

# Justification of Minimum Entropy

- Assume true measurements are available:

$$\max_{\pi} - \sum_{i=1}^m \sum_{j=1}^n \sum_{k=1}^c \pi_{ijk} \ln \pi_{ijk}$$

Subject to

$$\sum_{i=1}^m \pi_{ijk} = \sum_{i=1}^m \pi_{ijk}^* \quad \text{true measurements}$$

$$\sum_{j=1}^n y_{jl} \pi_{ijk} = \sum_{j=1}^n y_{jl} \pi_{ijk}^*$$

# Justification of Minimum Entropy

- *Theorem.* Minimizing the KL divergence

$$\ell(\pi^*, \pi) = \sum_{i=1}^m \sum_{j=1}^n D_{\text{KL}}(\pi_{ij}^* \parallel \pi_{ij})$$

is equivalent to minimize entropy.

# Lagrangian Dual

- The Lagrangian dual can be written as

$$L = - \sum_{i=1}^m \sum_{j=1}^n \sum_{k=1}^c \pi_{ijk} \ln \pi_{ijk} + \sum_{i=1}^m \sum_{j=1}^n \lambda_{ij} \left( \sum_{k=1}^c \pi_{ijk} - 1 \right) \\ + \sum_{j=1}^n \sum_{k=1}^c \tau_{jk} \sum_{i=1}^m (\pi_{ijk} - z_{ijk}) + \sum_{i=1}^m \sum_{k=1}^c \sum_{l=1}^c \sigma_{ikl} \sum_{j=1}^n y_{jl} (\pi_{ijk} - z_{ijk})$$

Lagrangian multipliers

# Lagrangian Dual

- KKT conditions lead to a closed-form:

$$\pi_{ijk} = \frac{1}{Z} \exp \left\{ \tau_{jk} + \sum_l y_{jl} \sigma_{ikl} \right\}$$

$Z$  is the normalization factor given by

$$Z = \sum_k \exp \left\{ \tau_{jk} + \sum_l y_{jl} \sigma_{ikl} \right\}$$



# Worker Expertise & Task Confusability

- Explanation of dual variables:

$$\pi_{ijk} = \frac{1}{Z} \exp \left\{ \tau_{jk} + \sum_l y_{jl} \sigma_{ikl} \right\}$$

item confusability

worker expertise

# Measurement Objectivity: Item

- *Objective item confusability.* The difference of difficulty between labeling two items should be independent of the chosen workers
- *Mathematical formulation.* Let

$$c(i, j, k) = \frac{\mathbb{P}(Z_{ij} = k | Y_j = l)}{\mathbb{P}(Z_{ij} = l | Y_j = l)}$$

Then the ratio  $c(i, j, k)/c(i', j, k)$  should be Independent of the choices of  $i, i'$

# Measurement Objectivity: Worker

- *Objective worker expertise.* The difference of expertise between two workers should be independent of the item being labeled
- *Mathematic Formulation.* Let

$$c(i, j, k) = \frac{\mathbb{P}(Z_{ij} = k | Y_j = l)}{\mathbb{P}(Z_{ij} = l | Y_j = l)}$$

Then the ratio  $c(i, j, k)/c(i, j', k)$  should be Independent of the choices of  $j, j'$

# The Labeling Model Is Objective

*Theorem.* For deterministic labels, the labeling model given by

$$\pi_{ijk} = \frac{1}{Z} \exp \left\{ \tau_{jk} + \sum_l y_{jl} \sigma_{ikl} \right\}$$

uniquely satisfies the measurement objectivity principle

# Constraint Relaxation

$$\sum_{i=1}^m \pi_{ijk} \approx \sum_{i=1}^m z_{ijk}$$

**For each item:**

Count # workers labeling it as class 1

Count # workers labeling it as class 2

column matching

	Item 1	Item 2	Item 3	Item 4	Item 5	Item 6
Worker 1	1	2	1	1	1	2
Worker 1	2	2	1	2	1	1
Worker 3	1	1	2	1	1	2
Worker 4	1	1	1	1	1	2
Worker 5	1	1	1	2	2	2

# Constraint Relaxation

$$\sum_{j=1}^n y_{jl} \pi_{ijk} \approx \sum_{j=1}^n y_{jl} z_{ijk}$$

row matching

**For each worker:**

Count # misclassifications from class 1 to 2

Count # misclassifications from class 2 to 1

	Item 1	Item 2	Item 3	Item 4	Item 5	Item 6
Worker 1	1	2	1	1	1	2
Worker 1	2	2	1	2	1	1
Worker 3	1	1	2	1	1	2
Worker 4	1	1	1	1	1	2
Worker 5	1	1	1	2	2	2

# Constraint Relaxation

$$\min_y \max_{\pi, \xi, \zeta} - \sum_{i=1}^m \sum_{j=1}^n \sum_{k=1}^c \pi_{ijk} \ln \pi_{ijk} - \sum_{j=1}^n \sum_{k=1}^c \frac{\xi_{jk}^2}{2\alpha} - \sum_{i=1}^m \sum_{k=1}^c \sum_{l=1}^c \frac{\zeta_{ikl}^2}{2\beta}$$

Subject to

$$\sum_{i=1}^m \pi_{ijk} = \sum_{i=1}^m z_{ijk} + \xi_{jk}$$

$$\sum_{j=1}^n y_{jl} \pi_{ijk} = \sum_{j=1}^n y_{jl} z_{ijk} + \zeta_{ikl}$$

Relaxing moment constraints to prevent overfitting

# Implementation

- Convert the primal problem to its dual form
- Coordinate descent
  - Split the variables into two blocks:  $\{y\}, \{\tau, \sigma\}$
  - Each subproblem is convex and smooth
  - Initialize ground truth by majority vote



# Model Selection

- $k$ -fold cross validation to choose  $(\alpha, \beta)$ 
  - Split the data matrix into  $k$  folds
  - Each fold used as a validation set once
  - Compute average likelihood over validations

We don't need ground truth for model selection!

# Experiments: Image Labeling

- 108 bird images, 2 breeds, 39 workers
- Each image was labeled by all workers



From: P. Welinder, S. Branson, S. Belongie and P. Perona. The Multidimensional Wisdom of Crowds. NIPS 2010.

# Experiments: Image Labeling

- Experimental results (accuracy, %)

Worker Number	10	20	30
Minimax Entropy	85.18	92.59	93.52
Dawid & Skene	79.63	87.04	87.96
Dawid & Skene (S)*	45.37	57.41	75.93
Majority Voting	67.59	83.33	76.85
Average Worker	62.78		

\* Dawid & Skene (S): simplified Dawid and Skene's method

# Experiments: Image Labeling

- Experimental results (accuracy, %)

Worker Number	10	20	30
Minimax Entropy	85.18	92.59	93.52
Dawid & Skene	79.63	87.04	87.96
Dawid & Skene (S)	45.37	57.41	75.00
Majority Voting	67.59	83.33	76.85
Average Worker	62.78		

It is risky to model worker expertise by a single number

# Experiments: Web Search

- 177 workers and 2665 <query, URL> pairs
- 5 classes: perfect, excellent, good, fair and bad
- Each pair was labeled by 6 workers

Minimax Entropy	88.84
Dawid & Skene	84.09
Majority Voting	77.65
Average worker	37.05

# Comparing with More Methods

- Other methods: Raykar et al (JMLR 2010, adding beta/Dirichlet prior), Welinder et al (NIPS 2010, matrix factorization), Karger et al (NIPS, 2011, BP-like iterative algorithm)
- From the evaluation in (Liu et al. NIPS 2012)
  - None of them can outperform Dawid and Skene's
  - Karger et al (NIPS, 2011) is even much worse than majority voting

# 3. Future Work and Conclusion

# Budget-Optimal Crowdsourcing

- Assume that we have a budget to get 6 labels. **Which one deserves another label, item 2 or 3?**
- How about having a budget of 7 labels or even more?

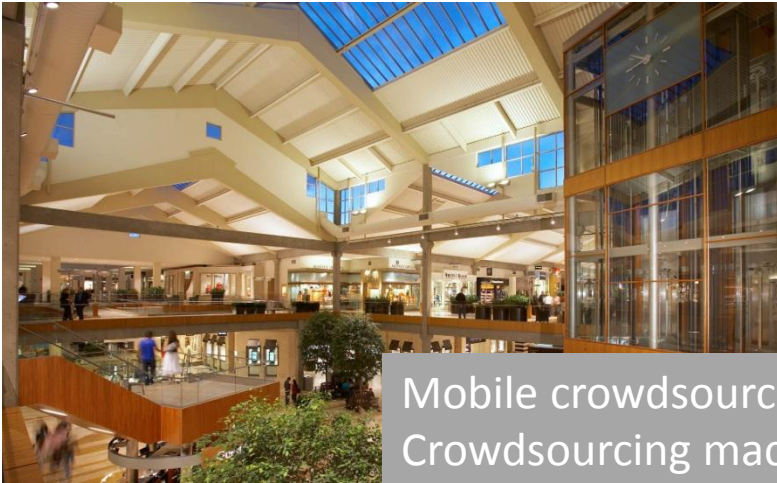
	1 <sup>st</sup> round	2 <sup>nd</sup> round
Item 1	1	1
Item 2	1	-1
Item 3	1	



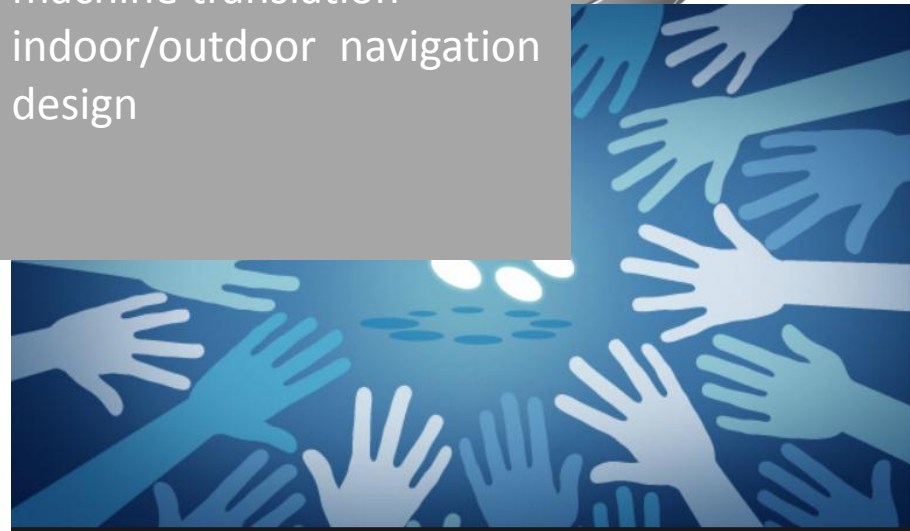
# Contextual Minimax Entropy

- Contextual information of items and workers
- (An example) Label a web page as *spam* or *nospam* by a group of workers
  - For each web page: its URL ends with .edu or not, popularity of its domain, creating time
  - For each worker: education degree, reputation history, working experience

# Beyond Labeling



Mobile crowdsourcing platform  
Crowdsourcing machine translation  
Crowdsourcing indoor/outdoor navigation  
Crowdsourcing design  
Wikipedia  
...



# ICML'13 Workshop

## Machine Learning Meets Crowdsourcing



**ICML | Atlanta**  
International Conference on Machine Learning

16-21 JUNE 2013 ATLANTA

[http://www.ics.uci.edu/~qliu1/MLcrowd\\_ICML\\_workshop/](http://www.ics.uci.edu/~qliu1/MLcrowd_ICML_workshop/)

# Summary

- Proposed minimax entropy principle for estimating ground truth from noisy labels
- Both task confusability and worker expertise are taken into account in our method
- Measurement objectivity is implied

# Acknowledgments

- Daniel Hsu (MSR New England)
- Xi Chen (Carnegie Mellon University)
- Gabriella Kazai (MSR Cambridge)
- Chris Burges (MSR Redmond)
- Chris Meek (MSR Redmond)