

A Stochastic Composite Gradient Method with Incremental Variance Reduction

Junyu Zhang (University of Minnesota)
and
Lin Xiao (Microsoft Research)

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Technical challenge and related work

- challenge: biased gradient estimator
 - denote $F(x) := f(g(x))$ where $g(x) \in \mathbf{E}[g_k(x)]$
 $F'(x) = [g'(x)]^T f'(g(x))$
 - subsampled estimators
$$y = \frac{1}{|\mathcal{S}|} \sum_{\xi \in \mathcal{S}} g_\xi(x), \quad z = \frac{1}{|\mathcal{S}|} \sum_{\xi \in \mathcal{S}} g'_\xi(x)$$
 - $\mathbf{E}[y] = g(x)$ and $\mathbf{E}[z] = g'(x)$, but $\mathbf{E}[z]^T f'(y) \neq F'(x)$
- related work
 - more general composite stochastic optimization (Wang, Fang & Liu 2017; Wang, Liu & Fang 2017; ...)
 - two-level composite finite-sum: extending SVRG and SAGA (Lian, Wang & Liu 2017; Huo, Gu, Liu & Huang 2018; Lin, Fan, Wang & Jordan 2018; Zhang & Xiao 2019, ...)

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Convergence analysis

- $$\text{minimize}_{x \in \mathbf{R}^d} f(\mathbf{E}[g_k(x)]) + r(x)$$
- assumptions
 - f is ℓ_f -Lipschitz and f' is L_f -Lipschitz
 - r convex but can be non-smooth
 - g_k and g'_k are mean-square Lipschitz with constants ℓ_g and L_g
 $\mathbf{E}[\|g_k(x) - g_k(y)\|^2] \leq \ell_g^2 \|x - y\|^2$
 $\mathbf{E}[\|g'_k(x) - g'_k(y)\|^2] \leq L_g^2 \|x - y\|^2$
 - g_k and g'_k have bounded variance
 $\mathbf{E}[\|g_k(x) - g(y)\|^2] \leq \sigma_g^2, \quad \mathbf{E}[\|g'_k(x) - g'(y)\|^2] \leq \sigma_g'^2$
 - sample complexity for $\mathbf{E}[\|\hat{g}(x)\|^2] \leq \epsilon$, where
$$\hat{g}(x) = \frac{1}{\eta} (x - \text{prox}'_\eta(x - \eta F'(x))) = F'(x) \text{ if } r \equiv 0$$

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Composite stochastic optimization

- composition with expectation

$$\text{minimize}_{x \in \mathbf{R}^d} f(\mathbf{E}[g_k(x)]) + r(x)$$
 - $f: \mathbf{R}^d \rightarrow \mathbf{R}$ smooth and possibly nonconvex
 - $g: \mathbf{R}^d \rightarrow \mathbf{R}^d$ smooth vector mapping for every ξ
 - $r: \mathbf{R}^d \rightarrow \mathbf{R} \cup \{\infty\}$ convex but possibly nonsmooth
- composition with finite sum

$$\text{minimize}_{x \in \mathbf{R}^d} f\left(\frac{1}{n} \sum_{i=1}^n g_i(x)\right) + r(x)$$
- applications beyond ERM
 - policy evaluation in reinforcement learning
 - risk-averse optimization, financial mathematics
 - ...

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Main results

- $$\text{minimize}_x \Psi(x) + r(x) \triangleq f(\mathbf{E}[g_k(x)]) + r(x)$$
- idea: use SARAH/SPIDER estimator for both $g(x)$ and $g'(x)$
- sample complexities
- | | assumptions: f and g_k Lipschitz and smooth, thus F smooth |
|---------------|--|
| F nonconvex | F ν -gradient dominant |
| r convex | F convex, r convex |
| | Φ μ -optimally strongly convex |
| E | $O(\epsilon^{-3/2})$ |
| Σ | $O(\min\{\epsilon^{-3/2}, n^{1/2} \epsilon^{-1}\})$ |
| | $O((n + \mu n^2) \log \epsilon^{-1})$ |
| | $O((n + \mu^{-1} n^2) \log \epsilon^{-1})$ |
- same as best complexities for problems without composition
 - lower bound $O(\min\{\epsilon^{-3/2}, n^{1/2} \epsilon^{-1}\})$ (Fang, Li, Lin & Zhang 2018)
 - composition (biased estimator) does not incur higher complexity

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List of convergence results

step size: $\eta \sim \frac{1}{L_F}$ where $L_F = \ell_g^2 L_f + \ell_f L_g$

structure	T	τ_r	S_r	B_r	sample complexity
expectation	$\frac{1}{\sqrt{\epsilon}}$	$\frac{1}{\sqrt{\epsilon}}$	$\frac{1}{\sqrt{n}}$	$\frac{n^2}{\epsilon}$	$O(\epsilon^{-3/2})$
finite-sum	$\frac{1}{\sqrt{\epsilon}}$	$\frac{1}{\sqrt{n}}$	$\frac{1}{\sqrt{n}}$	n	$O(n + \sqrt{n} \epsilon^{-1})$

F is ν -gradient dominant

expectation	$\frac{16n\sqrt{\epsilon}}{\nu}$	$\frac{1}{\sqrt{\epsilon}}$	$\frac{1}{\sqrt{n}}$	$\frac{12n^2}{\epsilon}$	$O(\nu \epsilon^{-1} \log \epsilon^{-1})$
finite-sum	$\frac{16n\sqrt{\epsilon}}{\sqrt{\nu}}$	$\frac{1}{\sqrt{n}}$	$\frac{1}{\sqrt{n}}$	n	$O\left(n + \frac{12n^2}{\nu} \log \epsilon^{-1}\right)$

Φ is μ -optimally strongly convex

expectation	$\frac{52\sqrt{\epsilon}}{\mu \nu}$	$\frac{1}{\sqrt{\epsilon}}$	$\frac{1}{\sqrt{n}}$	$\frac{8n^2}{\mu \epsilon}$	$O(\mu^{-1} \epsilon^{-1} \log \epsilon^{-1})$
finite-sum	$\frac{5}{\sqrt{\mu \eta \nu}}$	$\frac{1}{\sqrt{n}}$	$\frac{1}{\sqrt{n}}$	n	$O\left(n + \frac{8n^2}{\mu \nu} \log \epsilon^{-1}\right)$

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Examples

- policy evaluation with linear function approximation

$$\text{minimize}_{a \in \mathbf{R}^n} \|\mathbf{E}[A]x - \mathbf{E}[b]\|^2$$

A, b random, generated by MDP under fixed policy
- risk-averse optimization

$$\text{maximize}_{x \in \mathbf{R}^d} \underbrace{\frac{1}{n} \sum_{j=1}^n h_j(x)}_{\text{average reward}} - \lambda \underbrace{\left(\frac{1}{n} \sum_{j=1}^n (h_j(x) - \frac{1}{n} \sum_{i=1}^n h_i(x)) \right)^2}_{\text{variance of rewards (risk)}}$$

- often treated as two-level composite finite-sum optimization
- simple transformation using $\text{Var}(a) = \mathbf{E}[a^2] - (\mathbf{E}[a])^2$

$$\text{maximize}_{x \in \mathbf{R}^d} \frac{1}{n} \sum_{j=1}^n h_j(x) - \lambda \left(\frac{1}{n} \sum_{j=1}^n h_j^2(x) - \left(\frac{1}{n} \sum_{i=1}^n h_i(x) \right)^2 \right)$$

actually a one-level composite finite-sum problem

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Composite Incremental Variance Reduction (CIVR)

- input: $x_0^i, \eta > 0, T \geq 1, \{\tau_i, B_i, S_i\}$ for $i = 1, \dots, T$
- for $t = 0, \dots, T - 1$
- sample set B_t with size B_t and construct the estimates
$$y_t^i = \frac{1}{B_t} \sum_{\xi \in B_t} g_\xi(x_t^i), \quad z_t^i = \frac{1}{B_t} \sum_{\xi \in B_t} g'_\xi(x_t^i)$$
 - compute $\tilde{\nabla} F(x_t^i) = (z_t^i)^T f'(y_t^i)$ and let $x_t^{i+1} = \text{prox}'_{\eta} (x_t^i - \eta \tilde{\nabla} F(x_t^i))$
 - for $i = 0, \dots, \tau_t - 1$
 - sample a set S_t^i with size S_t^i and construct the estimates
$$y_t^{i+1} = y_t^i + \frac{1}{S_t^i} \sum_{\xi \in S_t^i} (g_\xi(x_t^{i+1}) - g_\xi(x_t^i))$$

$$z_t^{i+1} = z_t^i + \frac{1}{S_t^i} \sum_{\xi \in S_t^i} (g'_\xi(x_t^{i+1}) - g'_\xi(x_t^i))$$
 - compute $\tilde{\nabla} F(x_t^{i+1}) = (z_t^{i+1})^T f'(y_t^{i+1})$ and $x_t^{i+2} = \text{prox}'_{\eta} (x_t^{i+1} - \eta \tilde{\nabla} F(x_t^{i+1}))$
 - set $x_0^{t+1} = x_t^{\tau_t}$.
- output: \bar{x} randomly chosen from $\{x_t^i\}_{i=0, \dots, \tau_t-1}^{t=0, \dots, T-1}$

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Experiments on risk-averse optimization

- reduction of gradient norm
- reduction of objective value